

# Closure for Production Planning under Power Uncertainty Project

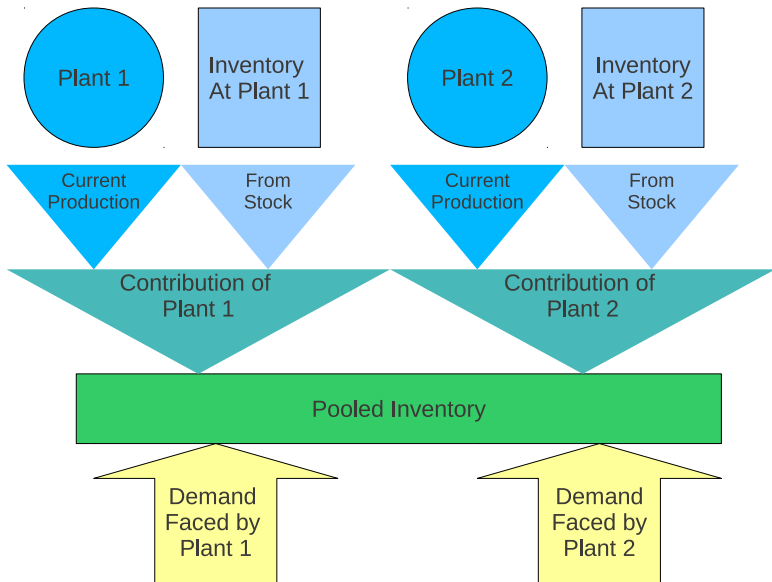
Lehigh University	Pietro Belotti	Çağrı Latifoğlu
	Fay Li	Larry Snyder
Air Products and Chemicals, Inc.		Jim Hutton
		Peter Connard

September 28, 2010 – EWO Meeting  
Carnegie Mellon University

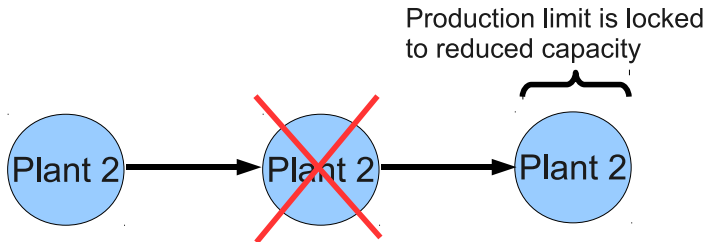
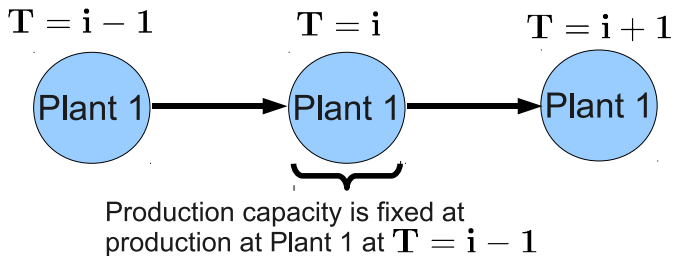
## Overview

- Critical resource for production is electricity
- Limited production and storage capacity
- 2 plants in consideration
- There is one common inventory pool
- Demand is satisfied from this pool
- ILC participation:
  - maximum number of interruptions are defined.
  - times of interruption are not known.
- Interruptions affect production modes.

# Setting



# Setting



# Polyhedral Uncertainty Set

Define

$$\xi_{t,p} = \begin{cases} 1 & \text{if an interruption occurs at time } t \text{ plant } p \\ 0 & \text{o.w.} \end{cases}$$

Then,

$$\mathcal{U} = \left\{ \xi_{t,p} \in \{0, 1\} \quad \forall (t,p) \in (T,P) \mid \sum_{p \in P} \xi_{t,p} \leq 1 \quad \forall t, \quad \sum_{t \in T, p \in P} \xi_{t,p} \leq K \right\}$$

## Scenarios

Each  $\xi \in \mathcal{U}$  corresponds to an interruption scenario.

There are exactly  $\binom{|T|}{|K|} \times |P|^{|K|}$  interruption scenarios.

Approach based on Soyster ('73), "solve" the inner problem by taking its dual.

- Consider the columnwise uncertainty
- Construct inner optimization problems (uncertainty embedded)
- Take the duals and embed dual feasibility constraints to outer model
- Enforce non-negativity on dual objectives
- Dual feasibility, dual optimality and primal feasibility will be satisfied when outer problem solution is optimal.

$$\text{minimize } \sum_{t \in T} \sum_{p \in P} \sum_{g \in G} c_{t,p,g} x_{t,p,g}$$

subject to

[prod. constraints]

$$\forall(t, g) \quad \sum_{p \in P} w_{t,p,g} \geq d_{t,g}$$

$$\forall(t, g) \quad \min_{\mathcal{U}} \left\{ \sum_{p \in P} inv_{t,p,g} \right\} \geq 0$$

$$\forall(t, p, g) \quad x_{t,p,g}, w_{t,p,g} \geq 0$$

# Duality Gap

Need to use strong LP duality, therefore relax integrality

$$\mathcal{U}^R = \left\{ \xi_{t,p} \in [0, 1] \quad \forall (t, p) \in (T, P) \mid \sum_{p \in P} \xi_{t,p} \leq 1 \quad \forall t, \quad \sum_{t \in T, p \in P} \xi_{t,p} \leq K \right\}$$

However in this case following holds since  $\mathcal{U} \subset \mathcal{U}^R$

$$\min_{\mathcal{U}^R} \left\{ inv_{t,p,g} \right\} \leq \min_{\mathcal{U}} \left\{ inv_{t,p,g} \right\}$$

Implies over-conservatism in the inner problems, **i.e. perceived severance of uncertainty is amplified!**



# Total Unimodularity

Consider the constraint matrix,  $\mathbf{A}$ , defined by  $\mathcal{U}$ . It has the following form:

$$\mathbf{A} = \begin{bmatrix} \mathbf{e}^T & & \\ \mathbf{I}_T & \dots & \mathbf{I}_T \\ & \mathbf{I}_{T \times P} & \end{bmatrix} = \begin{bmatrix} \hat{\mathbf{A}} \\ \mathbf{I}_{T \times P} \end{bmatrix}$$

where

$$\mathbf{e}^T = [1 \dots 1]_{T \times P} \text{ and } \hat{\mathbf{A}} = \begin{bmatrix} \mathbf{e}^T & & \\ \mathbf{I}_T & \dots & \mathbf{I}_T \end{bmatrix}$$

- $\hat{\mathbf{A}}$  is TUM by observation.
- Augmenting a matrix with  $\mathbf{I}$  does retain TUM property.

# A Numerical Example

Period			Product 1		
	Plant 1	Plant 2	Total Production	Inventory Pool	Demand
0	-	-	-	20000	-
1	0	63972	63972	185635	78337
2	0	63972	63972	136185	113422
3	0	63972	63972	27213	172944
4	63972	63972	127944	33108	122049
5	63972	63972	127944	13255	147796
6	63972	63972	127944	1154	140045
7	63972	63972	127944	0	129098

Period			Product 2		
	Plant 1	Plant 2	Total Production	Inventory Pool	Demand
0	-	-	-	20000	-
1	0	4544	4544	182458	22086
2	0	4544	4544	165034	21967
3	0	4544	4544	127328	42249
4	4544	4544	9087	80972	55444
5	4544	4544	9087	55594	34464
6	4544	4544	9087	26624	38057
7	4544	4544	9087	0	35711

## Inter-temporal impact of Interruption

An interruption in plant  $p$  at period  $t$

- triggers a “safety-mode” at the other plant
  - Production is fixed at the previous day’s production
- triggers a “recovery mode” for one period after the power is recovered
  - Production occurs at reduced rate

## The New Uncertainty Set

- Requires more binary variables to be able to distinguish different modes
- The interaction between safety-mode rule and recovery-mode rule cause interesting circumstances, i.e. “interruption streaks”
- New uncertainty set is no longer TUM

# Extended Model

$\xi_{t,p} = 1$ , if plant  $p$  is interrupted at time  $t$ ;

$\alpha_{t,p} = 1$ , if plant  $p$  is in safety mode at time  $t$ ;

$\beta_{t,p} = 1$ , if plant  $p$  is in recovery mode at time  $t$ ;

$\gamma_{t,p} = 1$ , if plant  $p$  is unaffected at time  $t$ ;

$\delta_{t,p} = 1$ , if  $\alpha_{t,p} \wedge \beta_{t,p} = 1$

$\eta_{t,p} = 1$ , if  $\alpha_{t,p} \wedge \neg\beta_{t,p} = 1$

$$\tilde{u} = \left\{ \begin{array}{lll} \sum_{t \in T} \sum_{p \in P} \xi_{t,p} = K & & \sum_{p \in P} \xi_{t,p} \leq 1 \quad \forall p \\ \alpha_{1,p} = 0 & \forall p & \alpha_{t,p} - \alpha_{t-1,p} - \xi_{t,\bar{p}} \geq -1 \quad \forall p \quad \forall t > 1 \\ \xi_{1,p} - \beta_{1,\bar{p}} = 0 & \forall p & \alpha_{t,p} - \gamma_{t-1,p} - \xi_{t,\bar{p}} \geq -1 \quad \forall p \quad \forall t > 1 \\ \gamma_{1,p} - \gamma_{t,\bar{p}} = 0 & \forall p & \alpha_{t,p} + \xi_{t,p} \leq 1 \quad \forall p \quad \forall t > 1 \\ \xi_{1,p} + \beta_{1,p} + \gamma_{1,p} = 1 & \forall p & \alpha_{t,p} - \xi_{t,\bar{p}} \leq 0 \quad \forall p \quad \forall t > 1 \\ \alpha_{2,p} - \beta_{1,\bar{p}} - \xi_{2,p} \geq -1 & \forall p & \alpha_{t,p} + \gamma_{t,p} \leq 1 \quad \forall p \quad \forall t > 1 \\ \beta_{t,p} - \xi_{t-1,p} + \xi_{t,p} \geq 0 & \forall p \quad \forall t > 1 & \delta_{t,p} - \alpha_{t,p} - \beta_{t,p} \geq -1 \quad \forall p \quad \forall t > 1 \\ \beta_{t,p} - \beta_{t-1,p} - \xi_{t,\bar{p}} \geq -1 & \forall p \quad \forall t > 1 & \delta_{t,p} - \alpha_{t,p} \leq 0 \quad \forall p \quad \forall t > 1 \\ \beta_{t,p} + \xi_{t,p} \leq 1 & \forall p \quad \forall t > 1 & \delta_{t,p} - \beta_{t,p} \leq 0 \quad \forall p \quad \forall t > 1 \\ \beta_{t,p} + \gamma_{t,p} \leq 1 & \forall p \quad \forall t > 1 & \eta_{t,p} - \alpha_{t,p} + \beta_{t,p} \geq 0 \quad \forall p \quad \forall t > 1 \\ \beta_{t,p} - \beta_{t-1,p} - \xi_{t-1,p} \leq 0 & \forall p \quad \forall t > 1 & \eta_{t,p} - \alpha_{t,p} \leq 0 \quad \forall p \quad \forall t > 1 \\ \eta_{t,p} + \delta_{t,p} + \gamma_{t,p} + \xi_{t,p} = 1 & \forall p \quad \forall t > 1 & \eta_{t,p} + \beta_{t,p} \leq 1 \quad \forall p \quad \forall t > 1 \end{array} \right.$$

$$\xi_{t,p}, \alpha_{t,p}, \beta_{t,p}, \gamma_{t,p}, \delta_{t,p}, \eta_{t,p} \in \{0, 1\} \quad \forall t, p$$

# New Duality Gap

$z^*(ROP^{new}) = 934776.3$ . Now we know the optimal solution, we can observe the duality gap in individual subproblems.

Note that we can give  $\mathbf{x}, \mathbf{w}$  as parameters to subproblems.

For instance consider  $IOP(7,1)$ , which is

$$\min_{\tilde{u}} \left\{ \sum_{p=1}^P \widetilde{inv}_{7,p,1} \right\}$$

Solutions of the  $DRIOP(7,1)$ ,  $RIOP(7,1)$  and  $IOP(7,1)$  are given below

$$\{z^*(DRIOP(7,1)) = 0\} = \{z^*(RIOP(7,1)) = 0\} < \{z^*(IOP(7,1)) = 4000\}$$

If we had a TU Matrix:

$$z^*(DRIOP(t,g)) = z^*(RIOP(t,g)) = z^*(IOP(t,g)) \quad \forall t,g$$

## Another Numerical Example

Consider the following scenario: plant 1 is interrupted at period 3, plant 2 is interrupted at period 4 and plant 1 is interrupted again at period 5. This would correspond to

$$\xi_{3,1} \wedge \xi_{4,2} \wedge \xi_{5,1} = 1 \implies x_{3,1,g} = x_{4,2,g} = x_{5,1,g} = 0 \quad \forall g \in \mathcal{G}$$

Due to safety-mode rule

$$x_{3,2,g} = x_{2,2,g} \quad \forall g \in \mathcal{G}$$

Due to recovery-mode rule

$$x_{4,1,g} = x_{1,g}^{rec} \quad \forall g \in \mathcal{G}$$

$$x_{5,2,g} = x_{2,g}^{rec} \quad \forall g \in \mathcal{G}$$

At optimality  $z^* = 832931$ .

If we had the complete interruption information at  $t=0$  then there would be no uncertainty. Let's call this problem  $OP^{det}$ .

When we solve  $OP^{det}$ , we obtain the solution given below where  $z^*(OP^{det}) = 753669$ .

## Folding Horizon Scheme (FHS)

- Re-solve at every time period
  - As time proceeds, newly acquired interruption information is used to refine the uncertainty set
  - The model tends to produce more in early periods so that future interruptions can be countered
- Helps us mitigate the overproduction caused by the duality gap between inner problem primal and dual

Now instead of using the robust solution obtained at  $t=0$ , we will use the FHS. The resulting production levels are given below where  $z^*(FHS) = 753669$  which is equal to  $z^*(OP^{det})$  as expected.

## New Project

- Our objective is to hedge the power against price and supply uncertainties.
- Currently studying how to construct such a power portfolio.

# Questions?

This research was supported in part by a grant from the Pennsylvania Infrastructure Technology Alliance (PITA).