



Global Optimization of Bilinear Generalized Disjunctive Programs

Juan Pablo Ruiz

Ignacio E. Grossmann

*Department of Chemical Engineering
Center for Advanced Process Decision-making
Carnegie Mellon University
Pittsburgh, PA 15213*

Non-Convex Discrete/Continuous Optimization Models

Mixed Integer Program (MIP)

- Most common non-linear discrete/continuous optimization model.
- Purely equation-based.
- If some functions in MIP are non convex → **non-convex MINLP**.

Generalized Disjunctive Program (GDP)

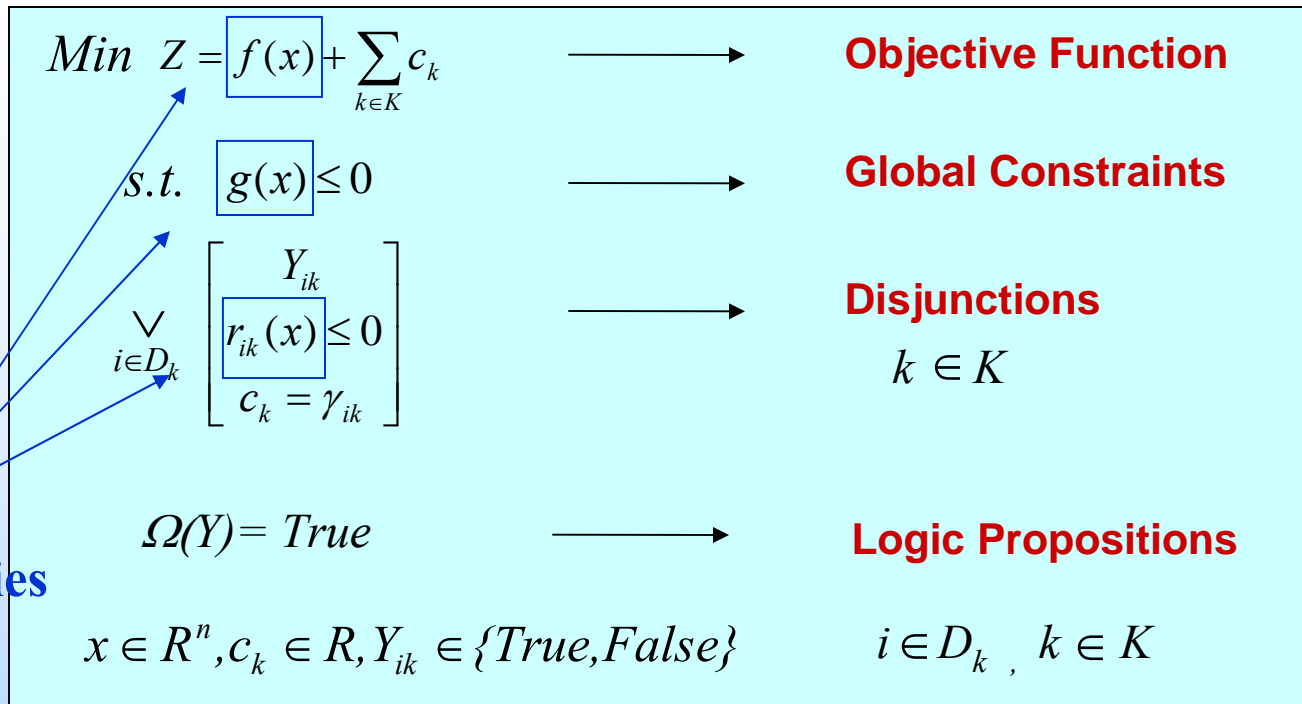
- Developed by Raman & Grossmann (1994)
- Combination of algebraic equations, disjunctions and logic propositions.
- Natural representation of engineering problems.
- If some functions in GDP are non convex → **non-convex GDP**.
- If all non linear functions are given by bilinear terms → **Bilinear GDP**.

Goal:

Global Optimization of Bilinear GDP with improved relaxations

Bilinear Generalized Disjunctive Programs

Bilinearities



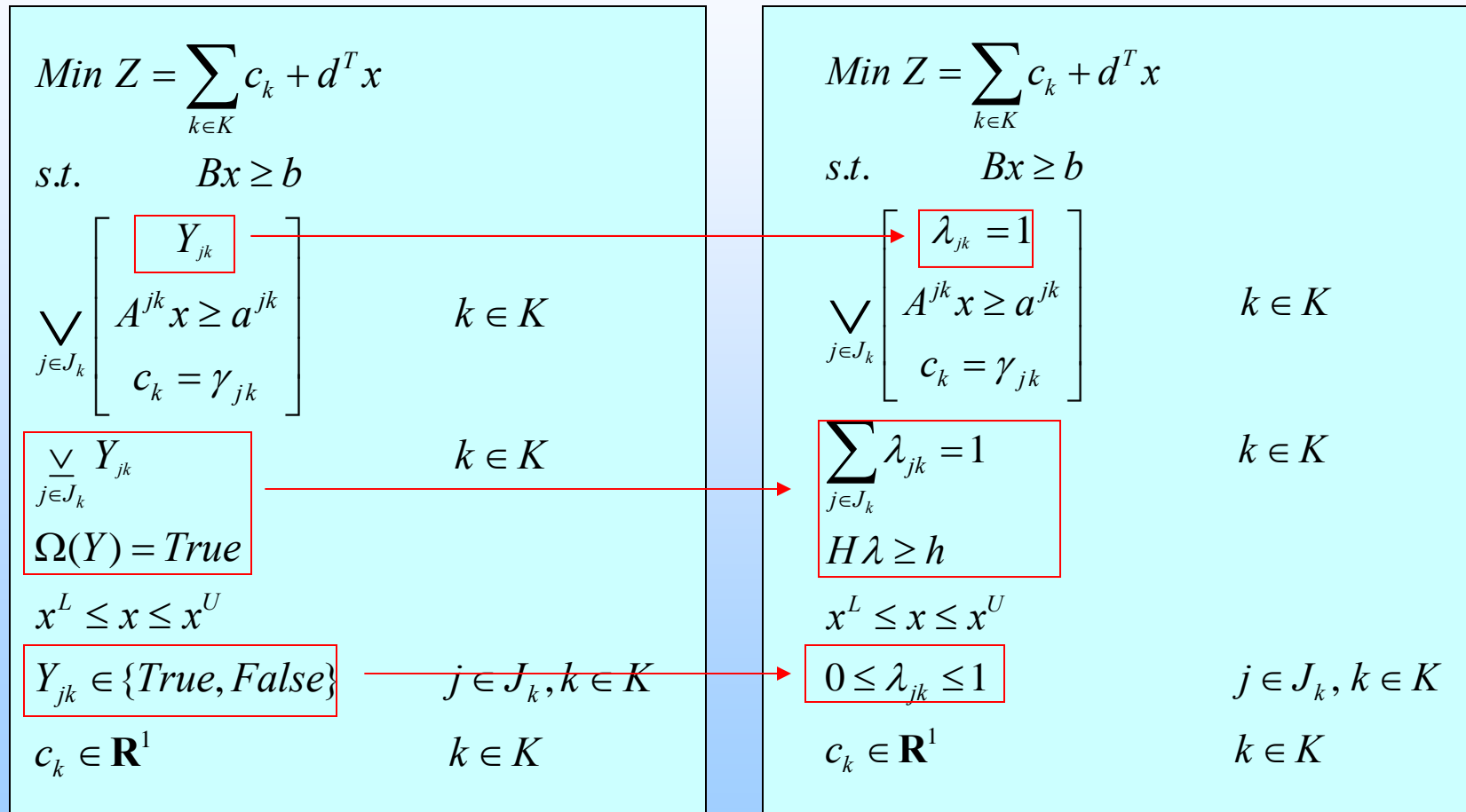
Process engineering models. (e.g. HENS, Water Treatment Networks, **Process Networks in general**)

Bilinearities may lead to multiple local minima \rightarrow **Global Optimization techniques are required**

Global optimization method by Lee & Grossmann (2001) \rightarrow *Is their relaxation the tightest?*

Relaxation of Bilinear terms using McCormick envelopes leads to a LGDP \rightarrow *Improved relaxations for Linear GDP has recently been obtained (Sawaya & Grossmann, 2007)*

Sawaya N.W. and Grossmann I.E. (2006)



LGDP

Integrality λ guaranteed

DP

Equivalent Disjunctive Programs

Regular Form (RF): form represented by intersection of unions of polyhedra

Thus the RF is:

$$F = \bigcap_{t \in T} S_t$$

where for $t \in T$, $S_t = \bigcup_{i \in Q_t} P_i$, P_i a polyhedron, $i \in Q_t$.

There exists many forms between CNF and DNF that are equivalent

Proposition 1 (Theorem 2.1 in Balas (1979)). *Let F be a disjunctive set in RF. Then F can be brought to DNF by $|T| - 1$ recursive applications of the following basic steps, which preserve regularity:*

For some $r, s \in T, r \neq s$, bring $S_r \cap S_s$ to DNF, by replacing it with:

$$S_{rs} = \bigcup_{\substack{i \in Q_r \\ t \in Q_s}} (P_i \cap P_t).$$

Illustrative Example: Basic Steps

$$F = S_1 \cap S_2 \cap S_3$$

$$S_1 = (P_{11} \cup P_{21}) \quad S_2 = (P_{12} \cup P_{22}) \quad S_3 = (P_{13} \cup P_{23})$$

Then F can be brought to DNF through 2 basic steps.

Apply Basic Step to:

$$S_1 \cap S_2 = (P_{11} \cup P_{21}) \cap (P_{12} \cup P_{22})$$

$$S_{12} = (P_{11} \cap P_{12}) \cup (P_{11} \cap P_{22}) \cup (P_{21} \cap P_{12}) \cup (P_{21} \cap P_{22})$$

We can then rewrite

$$F = S_1 \cap S_2 \cap S_3 \quad \text{as } F = S_{12} \cap S_3$$

Apply Basic Step to:

$$S_{12} \cap S_3 = ((P_{11} \cap P_{12}) \cup (P_{11} \cap P_{22}) \cup (P_{21} \cap P_{12}) \cup (P_{21} \cap P_{22})) \cap (P_{13} \cup P_{23})$$

$$S_{123} = \left(\begin{array}{l} (P_{11} \cap P_{12} \cap P_{13}) \cup (P_{11} \cap P_{22} \cap P_{13}) \cup (P_{21} \cap P_{12} \cap P_{13}) \cup (P_{21} \cap P_{22} \cap P_{13}) \\ \cup (P_{11} \cap P_{12} \cap P_{23}) \cup (P_{11} \cap P_{22} \cap P_{23}) \cup (P_{21} \cap P_{12} \cap P_{23}) \cup (P_{21} \cap P_{22} \cap P_{23}) \end{array} \right)$$

We can then rewrite

$$F = S_{12} \cap S_3 \quad \text{as } F = S_{123} \quad \text{which is its equivalent DNF} \quad 6$$

A Hierarchy of Relaxations for DP

Hull Relaxation (Balas, 1985):

Let us take the following disjunctive set:

$$F = \bigcap_{j \in T} S_j$$

Then the hull-relaxation corresponds to:

$$h\text{-rel } F := \bigcap_{j \in T} \text{clconv } S_j.$$

Proposition 3 (Theorem 4.3 in Balas (1979)): For $i = 0, 1, \dots, t$, let $F_i = \bigcap_{j \in T_i} S_j$ be a sequence of regular forms of a disjunctive set, such that

- i) F_0 is in CNF, with $P_0 = \bigcap_{j \in T_0} S_j$;
- ii) F_t is in DNF;
- iii) for $i = 1, \dots, t$, F_i is obtained from F_{i-1} by a basic step.

Then,

$$P_0 = h\text{-rel } F_0 \supseteq h\text{-rel } F_1 \supseteq \dots \supseteq h\text{-rel } F_t = \text{clconv } F_t. \quad (\text{true convex hull})$$

A Hierarchy of Relaxations for GDP

Proposition 4 (Sawaya & Grossmann, 2006) For $i = 1, 2, \dots, |T| + |K| - 1$ let F_{GDP_i} be a sequence of regular forms of the disjunctive set:

$$F = \left\{ z := (x, \lambda, c) \in \mathbf{R}^{n + \sum_{k \in K} |J_k| + |K|} : \bigcap_{i \in \bar{T}} \bar{b}^i z \geq \bar{b}_0^i \bigcap_{k \in \bar{K}} \bigcup_{j \in J_k} (\tilde{A}^{jk} z \geq \tilde{a}^{jk}) \bigcap_{n \in \hat{K}} \bigcup_{m \in J_n} (\hat{A}^{mn} z \geq \hat{a}^{mn}) \right\}, \text{ such that}$$

i) F_{GDP_0} corresponds to the disjunctive form:

$$F = \left\{ z := (x, \lambda, c) \in \mathbf{R}^{n + \sum_{k \in K} |J_k| + |K|} : \bigcap_{i \in \bar{T}} \bar{b}^i z \geq \bar{b}_0^i \bigcap_{k \in K} \bigcup_{j \in J_k} (\bar{A}^{jk} z \geq \bar{a}^{jk}) \right\};$$

ii) $F_{GDP_{|T|+|K|-1}} := F_t$ is in DNF;

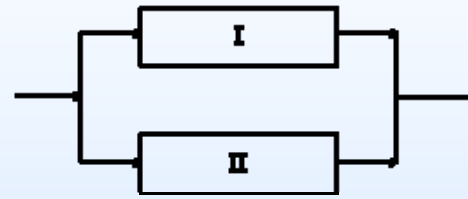
iii) for $i = 1, 2, \dots, |T| + |K| - 1$, F_{GDP_i} is obtained from $F_{GDP_{i-1}}$ by a basic step.

Then,

$$h\text{-rel } F_{GDP_0} \supseteq h\text{-rel } F_{GDP_1} \supseteq \dots \supseteq h\text{-rel } F_{GDP_{|T|+|K|-1}} = \text{clconv } F_{GDP_{|T|+|K|-1}} = \text{clconv } F_t. \text{ (true convex hull)}$$

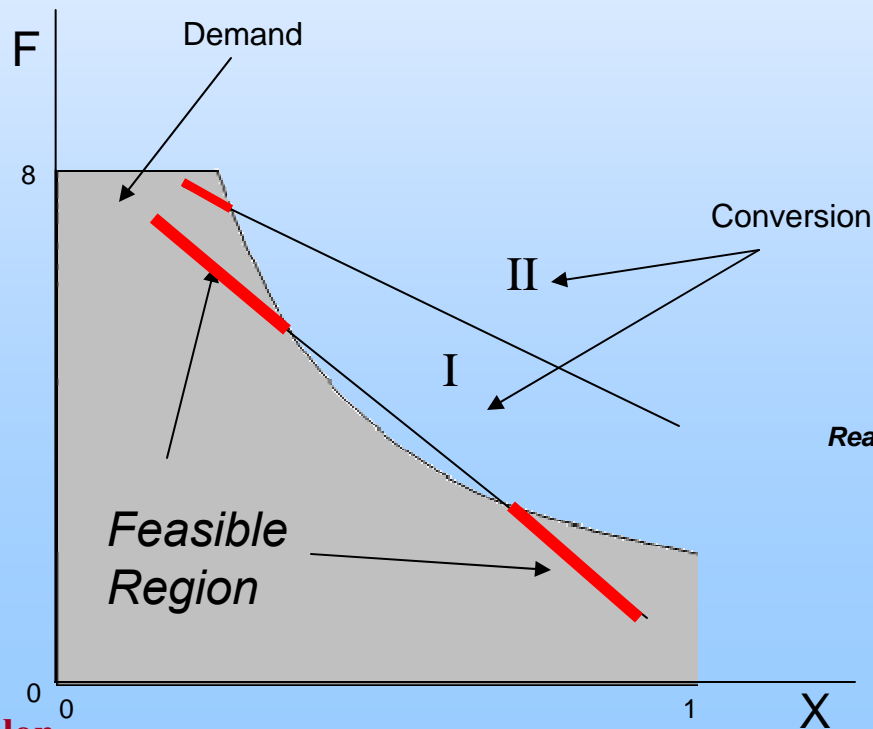
Bilinear GDP Relaxation

Illustrative Example: Optimal reactor selection



F : Flow
 X : Conversion

Feasible region
projected onto the FX space



GDP Formulation

Objective Function

$$\text{Max } Z = \theta FX - \gamma F - CP$$

Demand constraint

$$\text{s.t. } FX \leq d$$

$$\left[\begin{array}{c} Y_{11} \\ F = \alpha_1 X + \beta_1 \\ X_1^{LO} \leq X \leq X_1^{UP} \\ CP = Cp_1 \end{array} \right] \vee \left[\begin{array}{c} Y_{21} \\ F = \alpha_2 X + \beta_2 \\ X_2^{LO} \leq X \leq X_2^{UP} \\ CP = Cp_2 \end{array} \right]$$

Reactor Curves

$$Y_{11} \vee Y_{21} = \text{True}$$

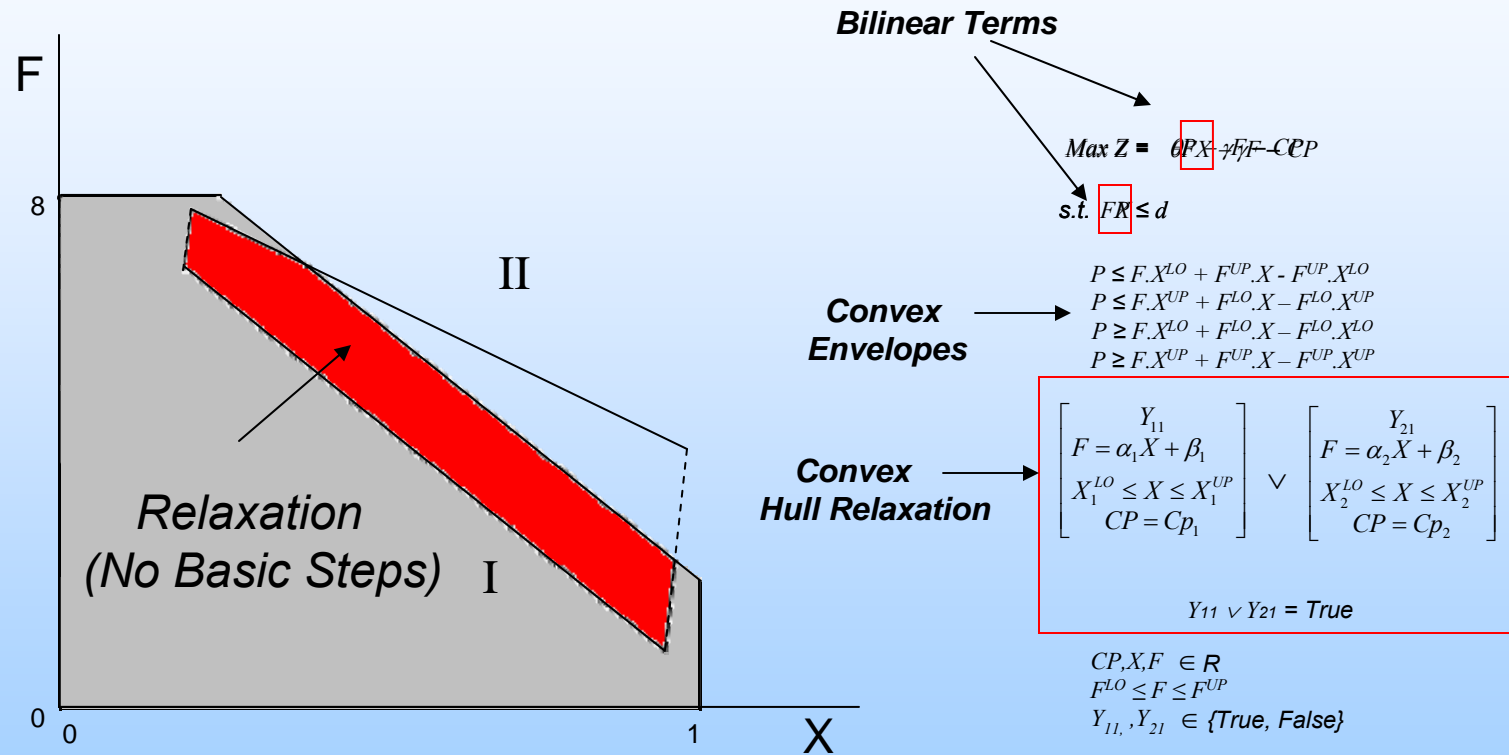
$$CP, X, F \in \mathbb{R}$$

$$F^{LO} \leq F \leq F^{UP}$$

$$Y_{11}, Y_{21} \in \{\text{True}, \text{False}\}$$

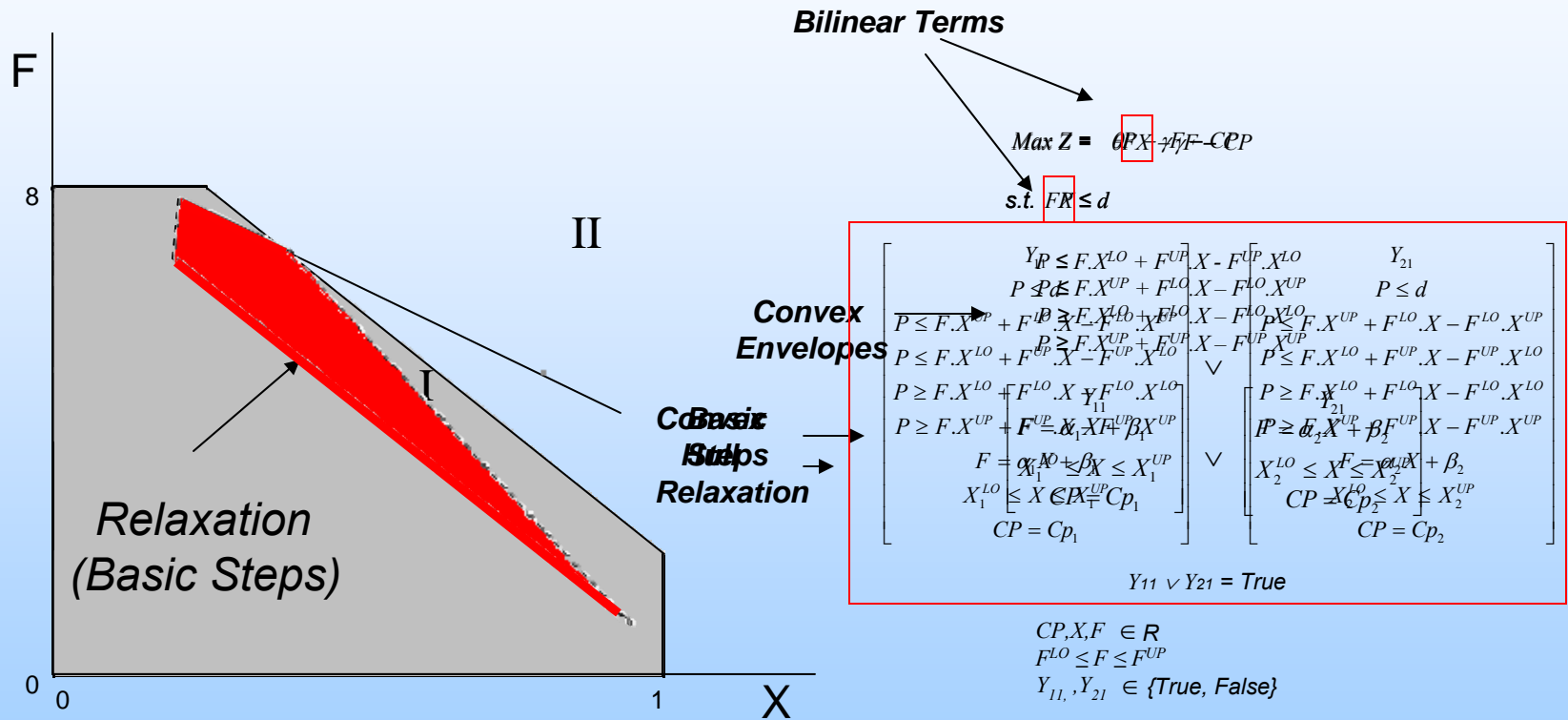
Bilinear GDP Relaxation

(Lee & Grossmann 2001)



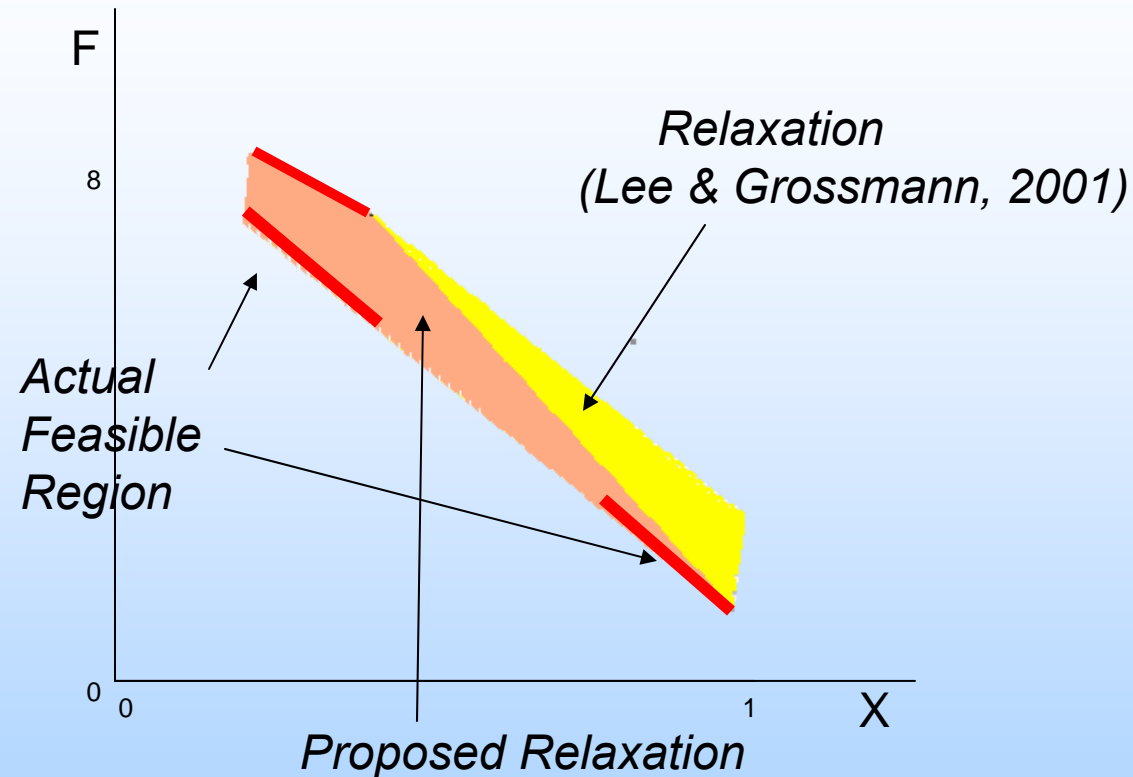
Bilinear GDP Relaxation

Proposed Relaxation



Bilinear GDP Relaxation

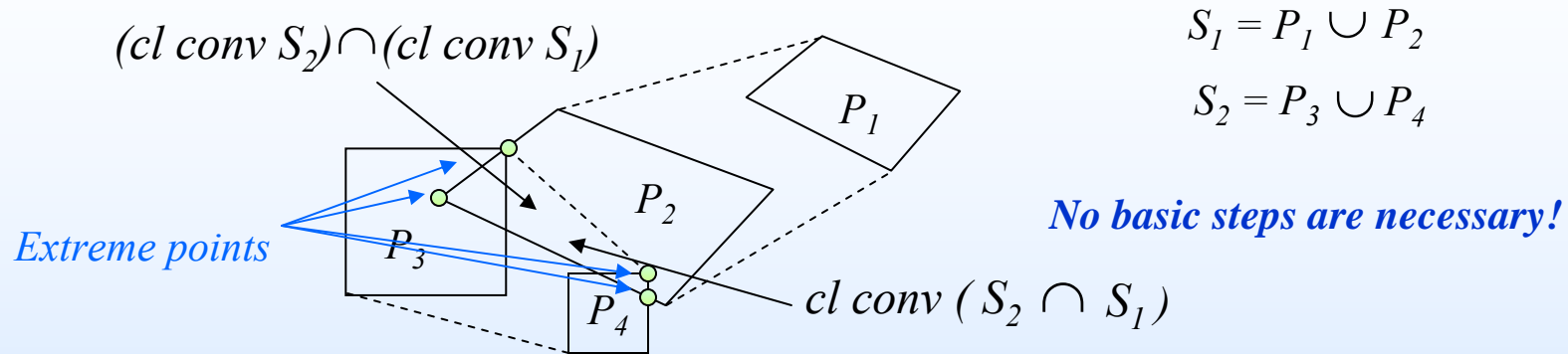
Comparison



The application of basic steps prior to the discrete relaxation leads to a **tighter** relaxed feasible region

Rules to apply basic steps. When they make a difference.

Motivating example:



Theorem 4.5. (Balas, 1985)

For $j=1,2$ let

$$S_j = \bigcup_{i \in Q_j} P_i,$$

Where each $P_i, i \in Q, j=1,2$, is a polyhedron. Then

$$cl\ conv(S_1 \cap S_2) = (cl\ conv\ S_1) \cap (cl\ conv\ S_2)$$

If and only if every extreme point (extreme direction) of $(cl\ conv\ S_1) \cap (cl\ conv\ S_2)$ is an extreme point (extreme direction) of $P_i \cap P_k$ for some $(i,k) \in Q_1 \times Q_2$

In general the hypothesis of the theorem is not easy to verify

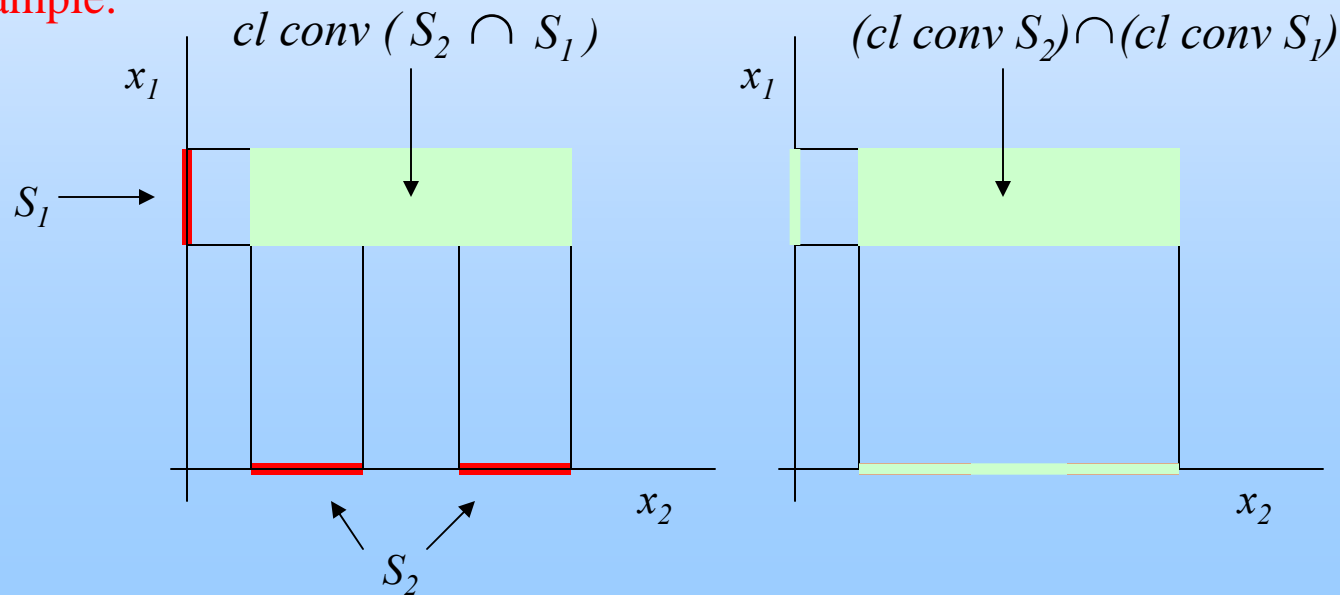
To gain insight, the structure of the program should be exploited

Proposition :

Let S_1 and S_2 be two disjunctions in which the variables restricted in S_i are not restricted in the S_j ($i=1,2 ; j=1,2$ and $i \neq j$)

Then the system satisfies the hypothesis of theorem 4.2.

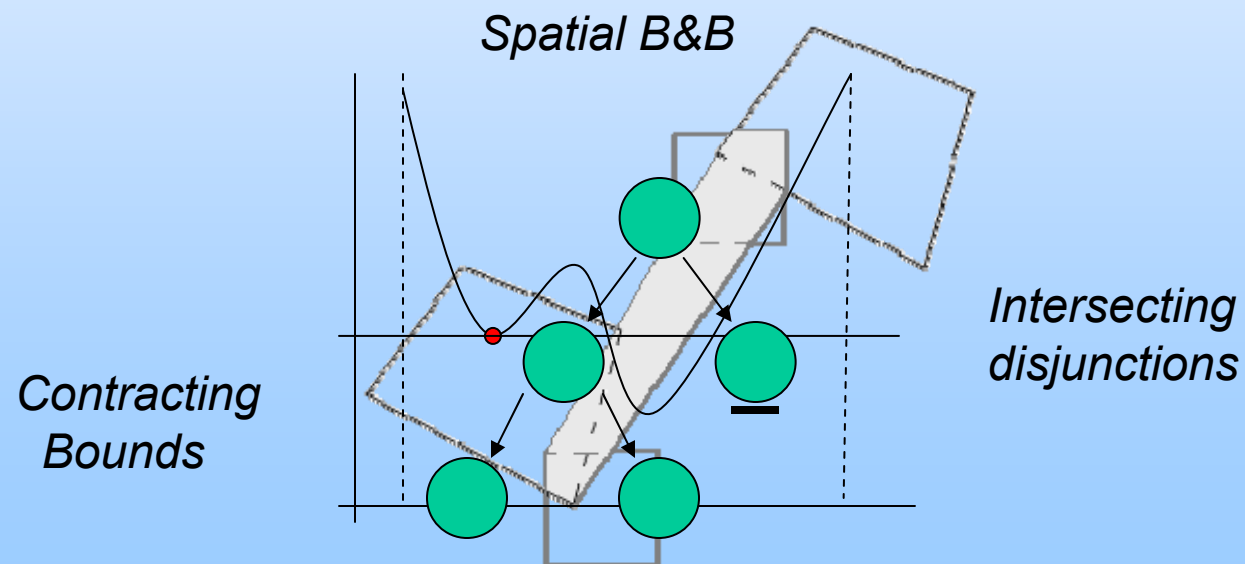
Example:



Summary of “practical” rules to apply basic steps

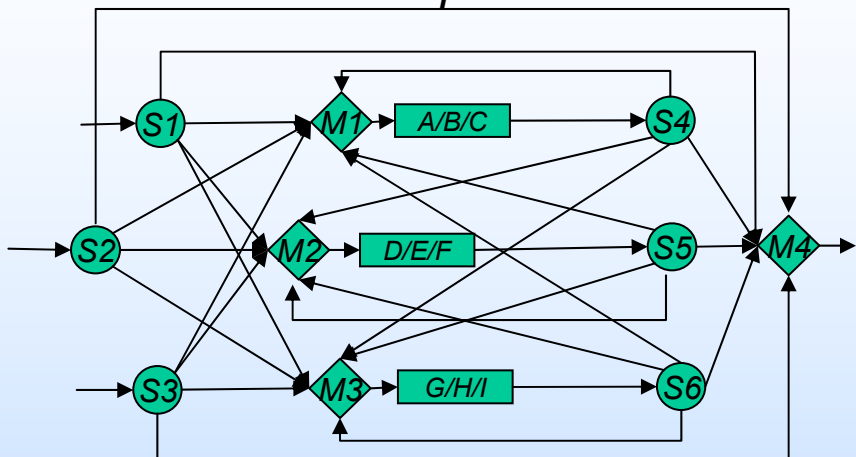
- Apply basic steps between those disjunctions with at least one variable in common.
- The more variables in common two disjunctions have the more the tightening expected
- If bilinearities are outside the disjunctions apply basic steps by introducing them in the disjunctions previous to the relaxation.
- If bilinearities are inside the disjunctions a less tightening effect is expected.
- A less increase in the size of the formulation is expected when basic steps are applied between improper disjunctions and proper disjunctions.

- Step 1: GDP reformulation (Apply basic steps following the rules presented)
- Step 2: Bound Contraction (Zamora & Grossmann, 1999)
- Step 3: Branch and Bound Procedure (Lee & Grossmann, 2001)



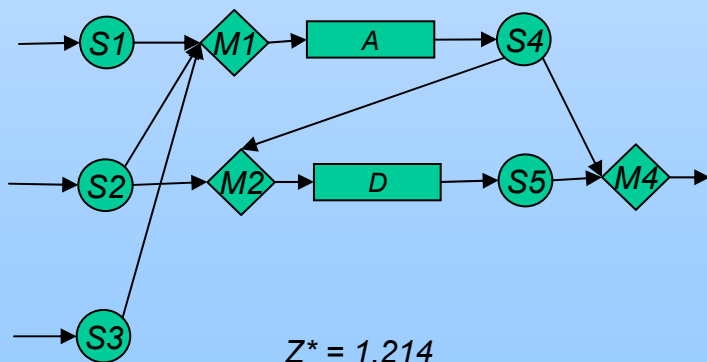
Case Study I: Water treatment network design

Process superstructure



N of cont. vars. : 114
 N of disc. vars. : 9
 N of bilinear terms: 36

Optimal structure



$Z^* = 1.214$

Generalized Disjunctive Program

$$\text{Min } Z = \sum_{k \in PU} CP_k$$

s.t.

$$f_k^j = \sum_{i \in M_k} f_i^j \quad \forall j \quad k \in MU$$

$$\sum_{i \in S_k} f_i^j = f_k^j \quad \forall j \quad k \in SU$$

$$\sum_{i \in S_k} \zeta_i^k = 1 \quad k \in SU$$

$$f_i^j = \zeta_i^k f_k^j \quad \forall j \quad i \in S_k \quad k \in SU$$

$$\bigvee_{h \in D_k} \left[\begin{array}{l} YP_k^h \\ f_i^j = \beta_k^{jh} f_i^j, i \in OPU_k, i' \in IPU_k, \forall j \\ F_k = \sum_j f_i^j, i \in OPU_k \\ CP_k = \partial_{ik} F_k \end{array} \right] \quad k \in PU$$

$$0 \leq \zeta_i^k \leq 1 \quad \forall j, k$$

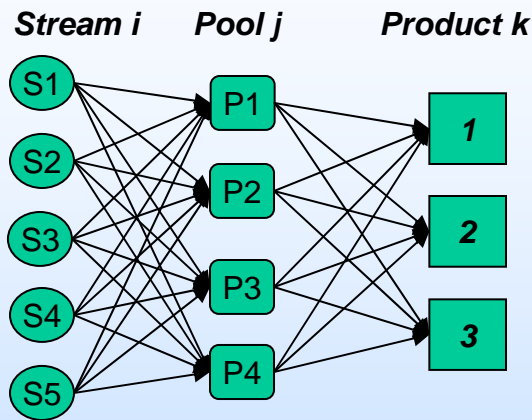
$$0 \leq f_i^j, f_k^j \quad \forall i, j, k$$

$$0 \leq CP_k \quad \forall k$$

$$YP_k^h \in \{true, false\} \quad \forall h \in D_k \quad \forall k \in PU$$

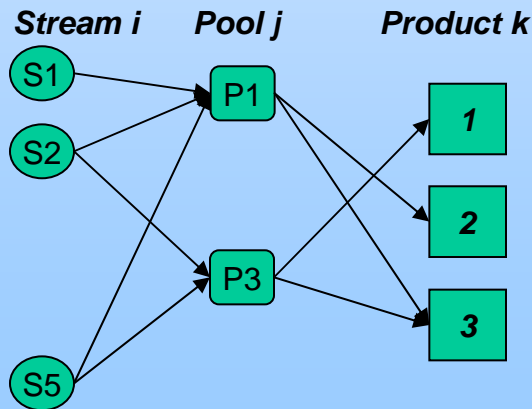
Case Study II: Pooling network design

Process superstructure



N of cont. vars. : 76
 N of disc. vars. : 9
 N of bilinear terms: 24

Optimal structure



$Z^* = -4.640$

Generalized Disjunctive Program

$$\text{Min } Z = \sum_{j \in J} CP_j + \sum_{i \in I} CST_i + \sum_{j \in J} \sum_{i \in I} c_{ij} \sum_{w \in W} f_{ijw} - \sum_{k \in K} d_k \sum_{j \in J} \sum_{w \in W} f_{jkw}$$

s.t.

$$\sum_{i \in I} \sum_{w \in W} f_{ijw} = \sum_{k \in K} \sum_{w \in W} f_{jkw} \quad \forall j \in J$$

$$\sum_{j \in J} \sum_{w \in W} f_{jkw} - S_k = 0 \quad \forall k \in K$$

$$f_{ijw} = \lambda_{iw} \sum_{w' \in W} f_{ijw'} \quad \forall i \in I, \forall j \in J, \forall w \in W$$

$$\sum_{j \in J} f_{jkw} - Z_{kw} \sum_{j \in J} \sum_{w' \in W} f_{jkw'} = 0 \quad \forall k \in K, \forall w \in W$$

$$\left[\begin{array}{c} YST_i \\ f^{lo} \leq \sum_{j \in J} \sum_{w \in W} f_{ijw} \\ CST_i = \alpha_i \end{array} \right] \vee \left[\begin{array}{c} -YST_i \\ f_{ijw} = 0 \\ CST_i = 0 \end{array} \right] \quad \forall i \in I$$

$$\left[\begin{array}{c} YP_j \\ f^{lo} \leq \sum_{i \in I} \sum_{w \in W} f_{ijw} \\ \sum_{k \in K} f_{jkw} = \sum_{i \in I} f_{ijw}, \forall w \in W \\ f_{jkw} = \zeta_j^k \sum_{i \in I} f_{ijw}, \forall w \in W, k \in K \\ \sum_{k \in K} \zeta_j^k = 1 \\ CP_j = \gamma_j \end{array} \right] \vee \left[\begin{array}{c} -YP_j \\ f_{ijw} = 0, \forall i \in I, w \in W \\ f_{jkw} = 0, \forall k \in K, w \in W \\ CP_j = 0 \end{array} \right] \quad \forall j \in J$$

$$0 \leq \zeta_j^k \leq 1; 0 \leq f_{jkw}, f_{ijw} \leq f^{up}$$

$$0 \leq CST_i, CP_j; YST_i, YP_j \in \{true, false\}$$

		<i>Global Optimization Technique using Lee & Grossmann relaxation</i>	<i>Global Optimization Technique using proposed relaxation</i>	<i>Relative Improvement</i>
<i>Example 1</i>	Initial Lower Bound	400.66	499.86	24.90%
	Bound contraction			99.7%
	Nodes	399	204	51%
		<i>Global Optimization Technique using Lee & Grossmann relaxation</i>	<i>Global Optimization Technique using proposed relaxation</i>	<i>Relative Improvement</i>
<i>Example 2</i>	Initial Lower Bound	-5515	-5468	0.90%
	Bound contraction			8%
	Nodes	748	683	9%



Conclusions and Remarks



- Tighter reformulation of bilinear GDPs.
- Proposed general rules to implement basic steps.
- Proposed methodology to solve Bilinear GDPs.
- Application in two cases showed improved performance.