



# Centralized versus Distributed Manufacturing: A Continuous Location-Allocation Problem

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# Motivation: Rethinking of traditional manufacturing

Distributed Manufacturing – geographically dispersed network of facilities

- Exploit new technology and modularity
- Attend new requirements of the market
- Logistical aspects

Potential applications

- Biomass supply chain (ethanol production)
- Shale gas supply chain (gas processing plants)
- Electric power generation (distributed power)







# **Motivation: Rethinking of traditional manufacturing**

#### Tradeoff: Capital cost vs. Transportation Cost

- · Potential advantages of Distributed Manufacturing
- Economy of scale favors large-scale production

#### Need for a general framework that captures the tradeoff and design best network

- · Evaluate cost of centralized versus distributed manufacturing
- Address higher level planning problems

#### Problem formulated as Capacitated Multi-facility Weber problem<sup>1</sup>

• Determine location in continuous 2-D space for new facilities in relation to the location of existing facilities



1 Brimberg, P. Hansen, N. Mladonovic, and S. Salhi, "A survey of solution methods for the continuous location allocation problem,", 2008.



# **Background: The Weber Problem**

## The Original Weber Problem (1909)<sup>2</sup>

- 2 suppliers, 1 market, and 1 facility
- Fixed points not colinear
- Euclidean distances
- Find facility location in 2-D space

## **Capacitated Multi-facility Weber Problem**

- · Facilities to be installed have maximum capacity
- Cooper (1972) was the first to attempt this problem<sup>3</sup>
  - Exact method: can only be applied for very small-problems
  - <u>Heuristic method</u>: Alternate the solution of the transportation and location problems until convergence. Do not guarantee optimality
- Sherali, Al-Lougani, Subramanian (2002) developed a Branch-and-Bound Algorithm<sup>4</sup>
- Several heuristic methods<sup>5</sup>

4 H. D. Sherali, I.Al-Loughani, and S. Subramanian, "Global Optimization Procedures for the Capacitated Euclidean and I p Distance Multifacility Location-allocation Problems,", 2002



<sup>2</sup> A.Weber and C. J. Friedrich, Theory of the Location of Industries, 1929.

<sup>3</sup> L. Cooper, "The Transportation-Location Problem," 1972.

<sup>5</sup> J. Brimberg, P. Hansen, N. Mladonovic, and S. Salhi, "A survey of solution methods for the continuous location allocation problem,", 2008.



## **Problem statement**

## Given:

- A set of suppliers i, a set of consumer markets j, and their respective fixed location, availability and demand
- M potential distributed and N potential centralized set of k single-product facilities, and their corresponding maximum capacity and conversion rate (unknown location)
- Investment, operating and transportation costs

## Find:

 Number, type and 2-D location of facilities to design a manufacturing network that minimizes the cost



Continuous variables:  $x_k$ ,  $y_k$ ,  $f_{ik}$ ,  $f_{kj}$ ,  $f_k$ ,  $D_{ik}$ ,  $D_{kj}$ Boolean variables:  $Z_k$ ,  $Z_{ik}$ ,  $Z_{kj}$ 



## **General Disjunctive Programming (GDP) Formulation**



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# Illustrative example: ethanol production





# Illustrative example: ethanol production

Intuitive answer: 1 centralized facility





# Illustrative example: ethanol production



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## **Illustrative example**

## **Computational results**

### **Global Optimization:**

METHOD	Cost $(10^3/week)$	CPU time (s)
BARON	503.9	703.2
SCIP	503.9	656.7
Multiparametric Disagreggation <sup>6</sup>	503.9	1,045.6
Bilevel decomposition	503.9	36.1

### **Convex relaxation (lower bound)**

METHOD	<b>Cost</b> $\binom{\$10^3}{week}$	CPU time (s)
McCormick	482.4	0.3
Piecewise McCormick <sup>7</sup> (16 partitions)	503.8	2065.5
Logarithmic Piecewise McCormick <sup>8</sup> (16 partitions)	503.8	35.9

6 S. Kolodziej, P. M. Castro, and I. E. Grossmann, "Global optimization of bilinear programs with a multiparametric disaggregation technique," J, 2013

7 P. M. Castro, "Tightening piecewise McCormick relaxations for bilinear problems,", 2014

8 R. Misener, J. P. Thompson, and C. a. Floudas, "Apogee: Global optimization of standard, generalized, and extended pooling problems via linear and logarithmic partitioning schemes," 2011

# **Bilevel decomposition: Background**

#### Global Logic-Based Outer Approximation (GLBOA)<sup>9</sup>

- Non-convex GDP
- <u>Master problem</u> (MP): linear relaxation of the nonconvex GDP
  - Lower Bound
- <u>Subproblem</u> (SP): lower dimensional nonconvex NLP in which the Boolean variables are fixed in the GDP
  - Upper bound
- Every time MP is resolved, an integer cut is added to exclude fixed discrete variables already used





# **Bilevel decomposition algorithm**

## Algorithm



## Description

#### <u>Master problem:</u> linear GDP relaxation provides a lower bound, and the selection of facilities to fix

- Bilinear terms are approximated using Logarithmic Piecewise McCormick<sup>10</sup>
- Distance constraints, which are convex, are linearized for a given discretization of space

# <u>Subproblem</u>: For the fixed alternative of facilities, the MINLP is solved with global solver to obtain an upper bound

• Potential links, which involve discrete variables, are still to be determined.

#### Integer cuts are added to the (MP)





![](_page_13_Picture_0.jpeg)

**Optimal network found: 10 distributed facilities** 

![](_page_13_Figure_3.jpeg)

![](_page_14_Picture_0.jpeg)

## **Computational results**

### **Global Optimization:**

METHOD	$\begin{array}{c} \textbf{Cost} \\ \binom{\$10^3}{week} \end{array}$	Optimality gap (%)	CPU time (hrs)
BARON	29,054	21%	12*
SCIP	29,892	92%	12*
Bilevel Decomposition	28,991	9%**	4*

\* Exceeded maximum CPU time

\*\* Estimated gap

For the Bilevel Decomposition Algorithm, the master problem (MILP) was solved using CPLEX and the subproblem (nonconvex MINLP) was solved using BARON

![](_page_15_Picture_0.jpeg)

![](_page_15_Figure_2.jpeg)

![](_page_16_Picture_0.jpeg)

**Optimal network found: 2 centralized + 1 distributed facilities** 

![](_page_16_Figure_3.jpeg)

![](_page_17_Picture_0.jpeg)

## **Computational results**

#### **Global Optimization:**

METHOD	Cost ( <sup>\$10³</sup> / <sub>week</sub> )	Optimality gap (%)	CPU time (hrs)
BARON	24,990	0.6%	12*
SCIP	25,181	7.6%	12*
Bilevel Decomposition	24,984	0.2%**	4*

\* Exceeded maximum CPU time

\*\* Estimated gap

For the Bilevel Decomposition Algorithm, the master problem (MILP) was solved using CPLEX and the subproblem (nonconvex MINLP) was solved using BARON

![](_page_18_Picture_0.jpeg)

## Conclusions

Nonconvex GDP reformulated as an MINLP

Commercial global solvers can solve small problems fairly easy

### Computationally expensive to solve large-scale problems

- Bilevel decomposition algorithm
  - Although at this point it cannot rigorously solve the large-scale problems to optimality, provides superior results
  - Potential to be improved

![](_page_19_Picture_0.jpeg)

## **Future work**

## Develop new cuts to tighten the relaxation

• Improve the performance of both the solvers and the algorithm

## **Rethink master problem formulation**

• So as it can be solved to optimality faster

## Apply formulation to different problem structures

- Investigate how the network configuration is affected by changes in the parameters
- Explore which conditions favor distributed and/or centralized manufacturing networks.

### Apply the model to biomass and electric power systems supply chain