

A Novel Global Optimization Approach to the Multiperiod Blending Problem

Scott Kolodziej

Advisor: Dr. Ignacio Grossmann

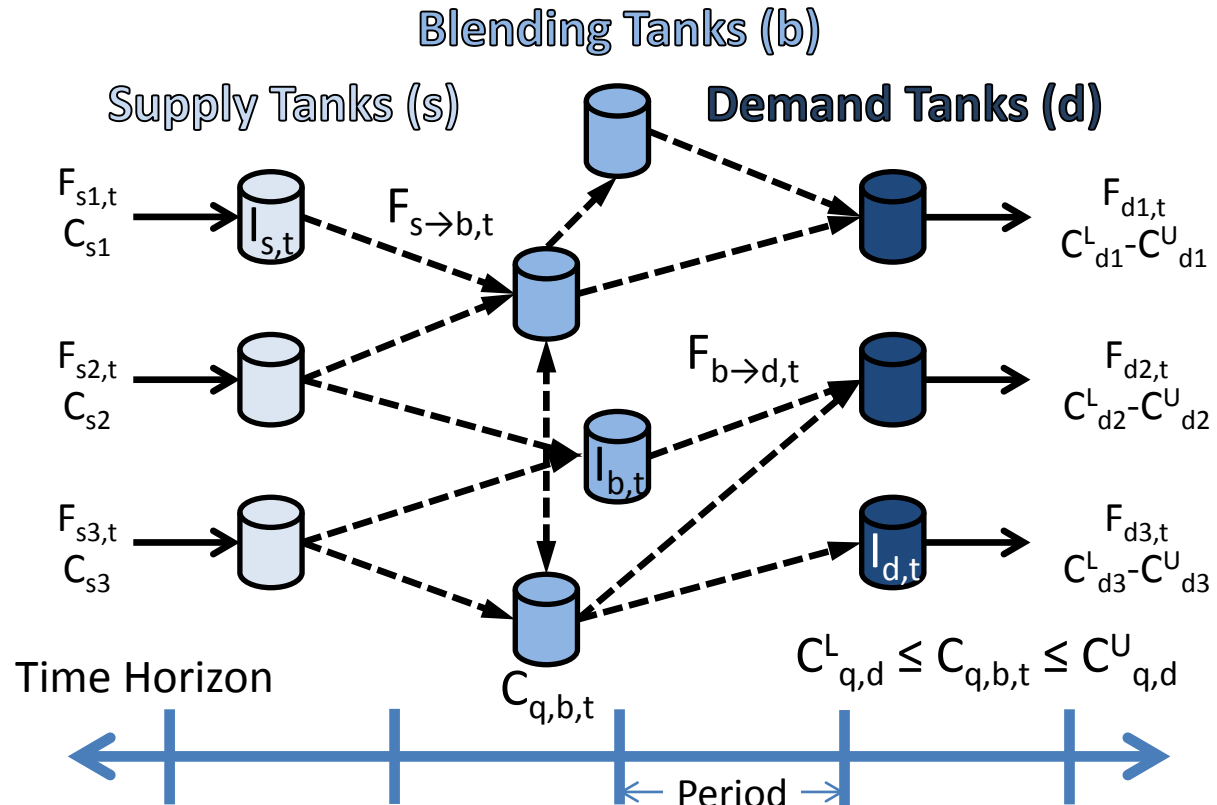
Department of Chemical Engineering

Carnegie Mellon University

ExxonMobil

Given Information

- **Time Horizon (Periods)**
- **Network Topology**
- **Supply Tanks**
 - Amount entering
 - Concentrations
- **Demand Tanks**
 - Amount withdrawn
 - Concentration limits
- **Initial Conditions**
 - Inventories
 - Concentrations
- **Economic Costs**
 - Network flow costs
 - Raw material costs
 - Profit for meeting demand



Determine

- Flows between which tanks in which time periods
- Inventories and concentrations for all tanks in each time period
- **Maximum total profit** of blending operation

Objective: Maximize Profit

- Mass Balances
 - Overall Flows
 - Individual Components (Blending)
- Flow/Inventory Bounds
- Operational Constraints
- Demand Specifications

Process
Constraints

Variables

- Flows, Concentrations, and Inventories (**Continuous**)
- Existence/Nonexistence of Streams (**Binary**)

Complicating **nonconvex bilinearities F·C and I·C** appear in
the individual component mass balances
Requires **global optimization** techniques

Resulting model is an **MINLP**

Given that $C = \sum_{k=p}^P \sum_{j=0}^9 10^k \cdot j \cdot z_{j,k}$ the bilinear product $u = F \cdot C$ can be replaced by this set of constraints using **exact linearization**:

F is
disaggregated
but still
continuous



$$\begin{aligned}
 u &= \sum_{k=p}^P \sum_{j=0}^9 10^k \cdot j \cdot \hat{F}_{j,k} \\
 \hat{F}_{j,k} &\leq F^U \cdot z_{j,k} && \forall k \in \{p, \dots, P\}, j \in \{0, \dots, 9\} \\
 \sum_{j=0}^9 \hat{F}_{j,k} &= F && \forall k \in \{p, \dots, P\} \\
 \sum_{j=0}^9 z_{j,k} &= 1 && \forall k \in \{p, \dots, P\} \\
 z_{j,k} &\in \{0, 1\} && \forall k \in \{p, \dots, P\}, j \in \{0, \dots, 9\}
 \end{aligned}$$

Teles, Castro, & Matos (2011)

Discretization **replaces bilinearity** with **mixed-integer linear constraints**

The **MINLP** model can be reformulated as an **MILP** approximation

Teles, Castro, & Matos (2011)

$$C = \sum_{k=p}^P \sum_{j=0}^9 10^k \cdot j \cdot z_{j,k}$$

0-1 Binary Variable
(one for each digit)

k selects over powers of 10

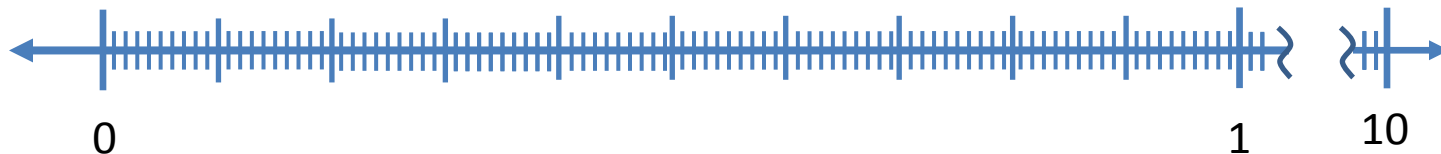
Radix (or base)

j selects over set of digits

$$\sum_{j=0}^9 z_{j,k} = 1 \quad \forall k \in \{p, \dots, P\}$$

Ensures only one digit for each decimal place

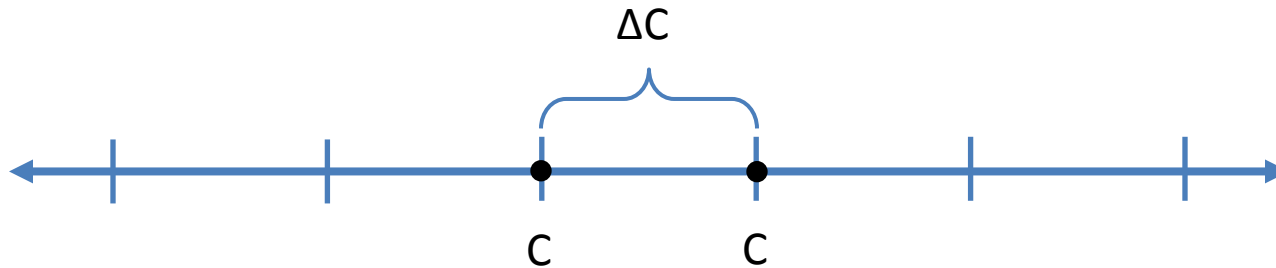
C Axis



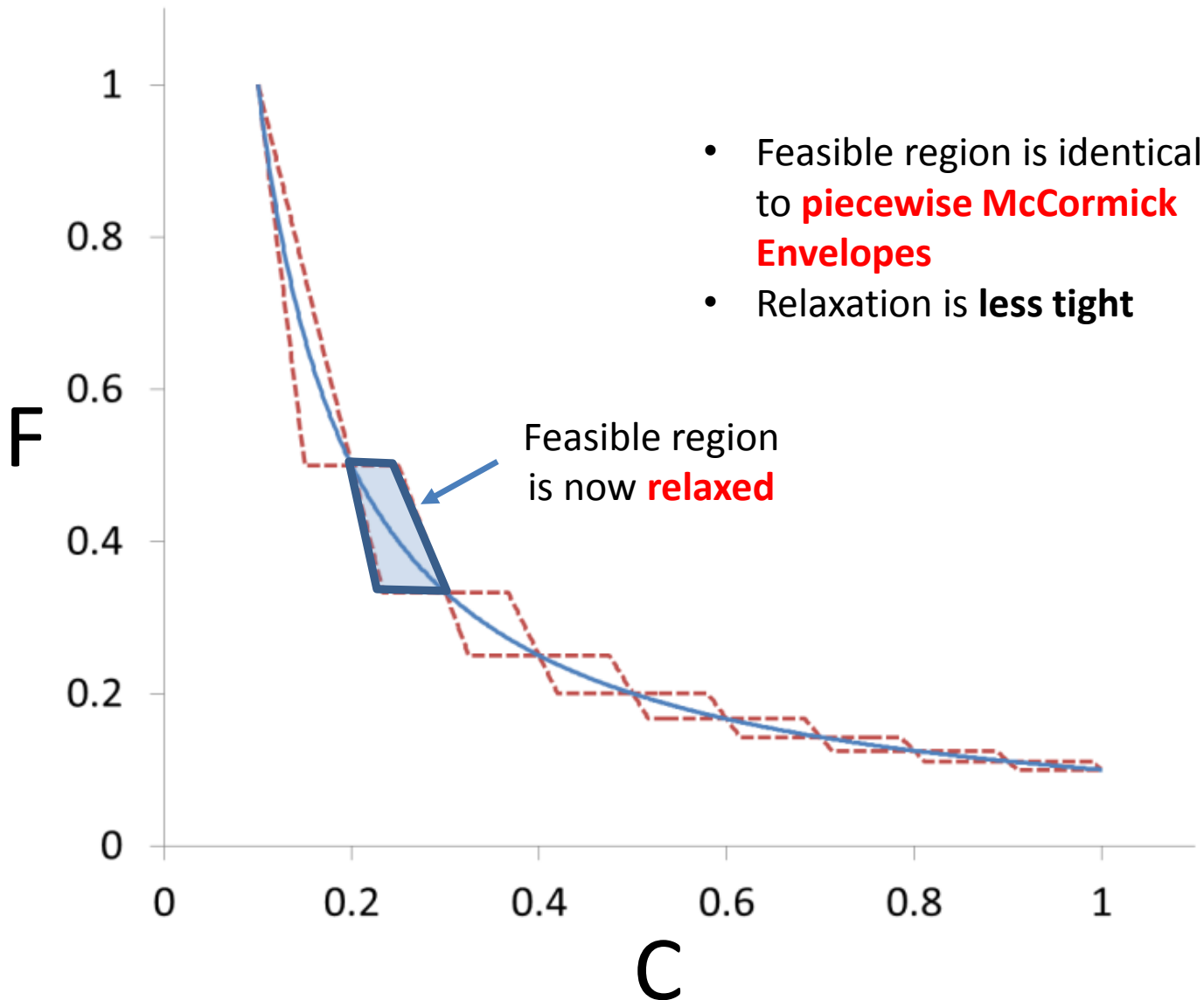
Increment	1	0.1	0.01
Range	0-9	0-9.9	0-9.99
Significant Digits	1	2	3
Binary Variables	10	20	30

Linear increase in binary variables for **order of magnitude** increase in precision

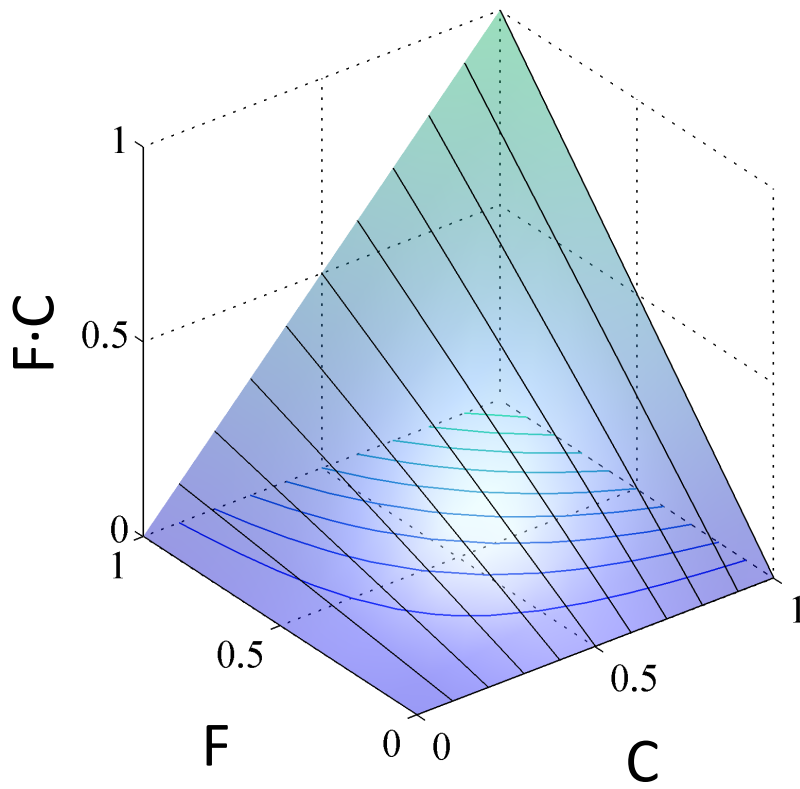
- RBD yields an **upper bound**
- What about a **lower bound**?



- We introduce ΔC as a **slack variable**
 - ΔC ranges between 0 and 10^p (the size of the “gaps”)
 - **Relaxed RBD constraints** can be added to “fill the gap” and **relax the original problem**

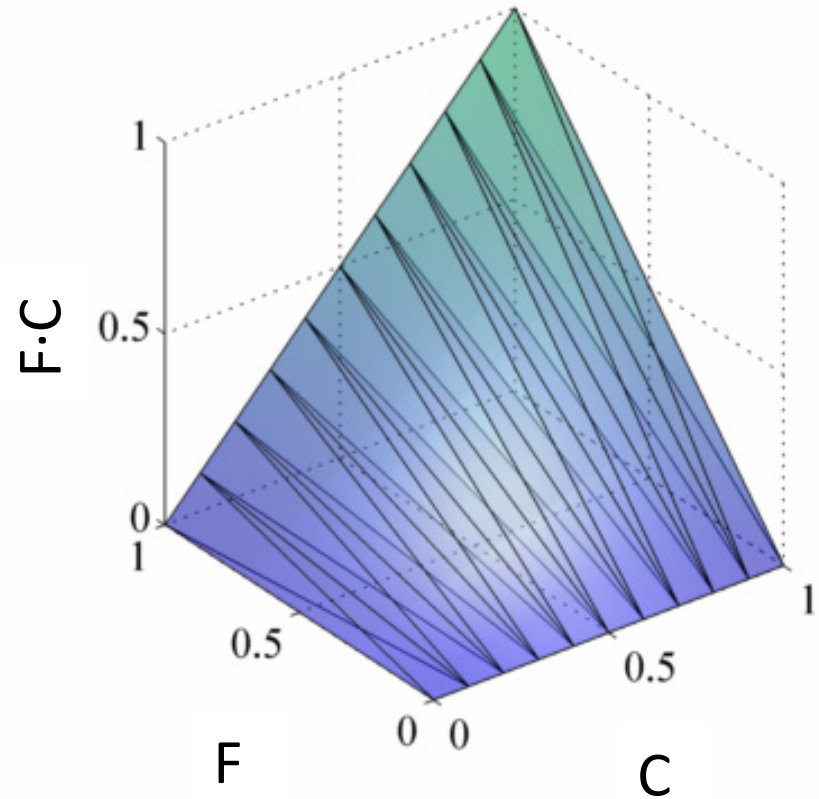


Upper Bounding



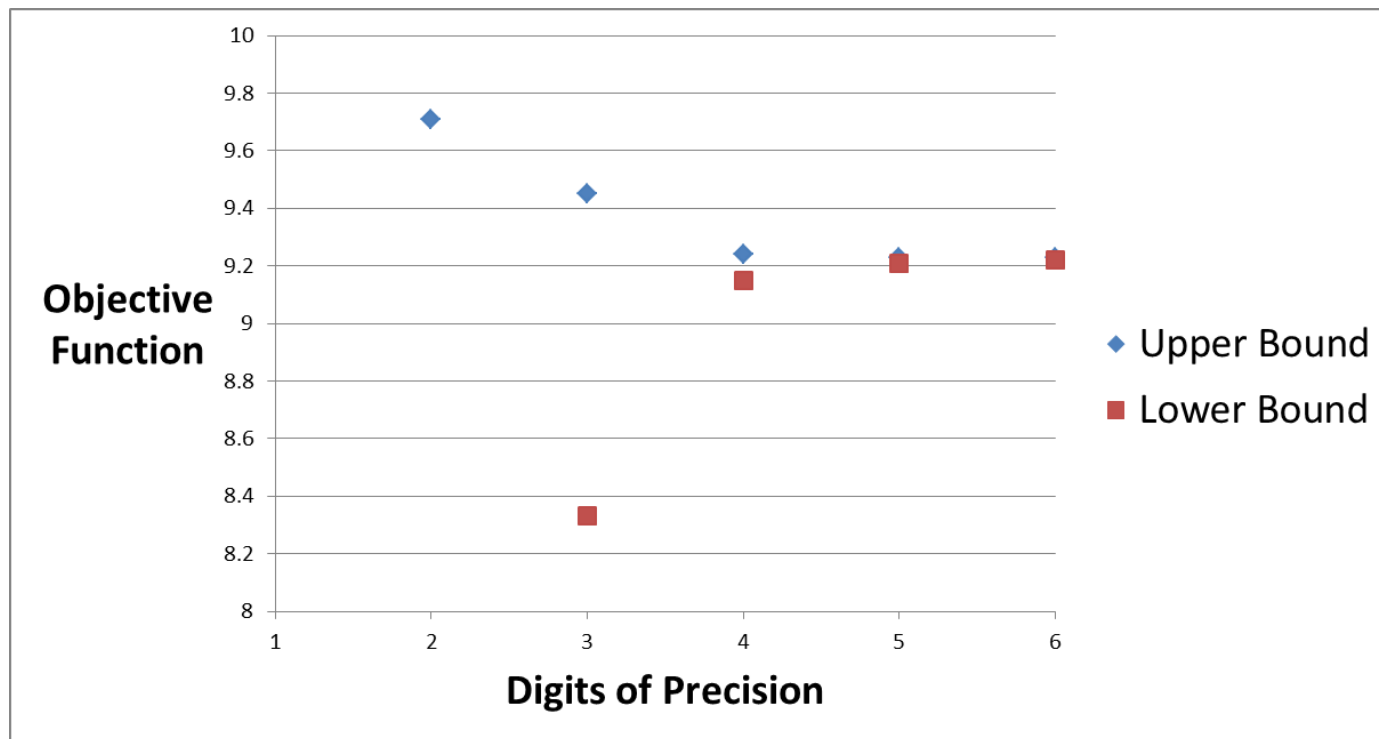
Underestimates the feasible region

Lower Bounding (Relaxation)



Overestimates the feasible region

- As **precision increases**, **UB** \rightarrow **LB**
- We can start with **low precision** and slowly **increase precision** until **gap** $< \epsilon$
- Currently **work in progress**



- Preliminary Computational Results

Tanks	6	8	8	8	8	8	8
Time Periods	3	3	3	3	4	4	4
Global Optimization Wall Time (s)	2.1	4753	2588	426	338	>7200	1525
MINLP Wall Time (s)	21.2	>7200	>7200	>7200	>7200	>7200	>7200
Upper Bound	13.3594	45.2843	7.3936	13.5268	53.9627	9.2266	20.0363
Lower Bound	13.3594	45.2608	7.3818	13.5268	53.9257	9.2051	19.9686
Relative Gap	0	5.19×10^{-4}	1.60×10^{-3}	0	6.86×10^{-4}	2.34×10^{-3}	3.39×10^{-3}
Iterations	2	4	4	4	4	4	4

Generally **much faster** than **MINLP**

Conclusions

- MINLP approach takes **too long**
- Effective **radix-based MILP approach** reviewed and expanded
 - **Order of magnitude reductions** in CPU time observed
- **Upper and lower bounds** were introduced using **radix-based discretization**

Future Work

- Utilize **upper/lower bounding** formulations to **globally optimize**
- Large scale instances may require **decomposition techniques**
 - Utilize **Lagrangean decomposition** to decompose larger problems into easier to solve **subproblems**