

Parallel Design of Experiments for Kinetic Parameter Estimation to Support Product Stability Predictions

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- Consumer products may be subject to prolonged storage and transportation times
 - ◆ Ensuring Product Quality and Stability is a critical and time-consuming activity
 - ◆ Shelf-lives typically measured in years
- Need to understand impact of formula design on product performance and stability
 - ◆ Undesirable chemical reactions may lead to product degradation
- Develop a suite of modeling tools to support the development of new consumer products:
 - ◆ Simulate product chemistry
 - ◆ Design efficient experimental campaigns
 - ◆ Discriminate among alternative models and estimate model parameters
 - ◆ Understand the uncertainty associated with model predictions

- CheK is a model library in gPROMS, developed and maintained by P&G
 - ◆ CheK allows for any combination of 8 kinetic models to form a complex reaction network
 - ◆ The reactor model is an isothermal batch reactor
 - ◆ For Product Stability applications, optimization for Parameter Estimation has been challenging in gPROMS
- The goal is to extend the current CheK capability by interfacing it with enhanced optimization tools and methods:
 - ◆ Integration using orthogonal collocation on finite elements
 - ◆ Simultaneous NLP solution using IPOPT
 - ◆ Open source modeling package PyOMO within Python platform
- The deliverable will be a flexible and robust application that can be maintained by P&G

- gPROMS has been successfully used for Process Engineering problems at P&G for approximately 16 years
 - ◆ More recent use has extended to Product Stability (PS) applications
- Initiated work on an actual Product Stability test problem
 - ◆ Validated gPROMS simulation results with optimization-based simulation
 - ◆ While results are similar, the PS problem is not well-scaled for optimization purposes using gPROMS internal units:
 - Concentrations are in $\mu\text{mol/L}$ vs mol/L
 - Time units are in days vs sec
 - Some constraints were merely satisfied due to small variable numeric values (constraint feasibility tolerance $4\text{E}-10$)
 - Small concentration values were also causing function errors for exponentiation in rate expressions

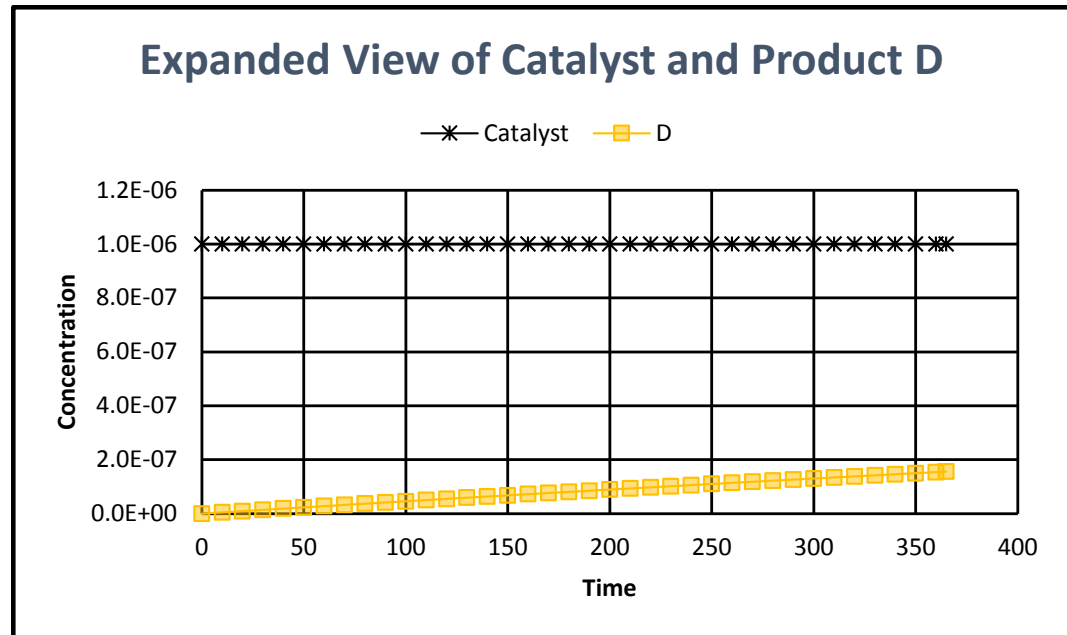
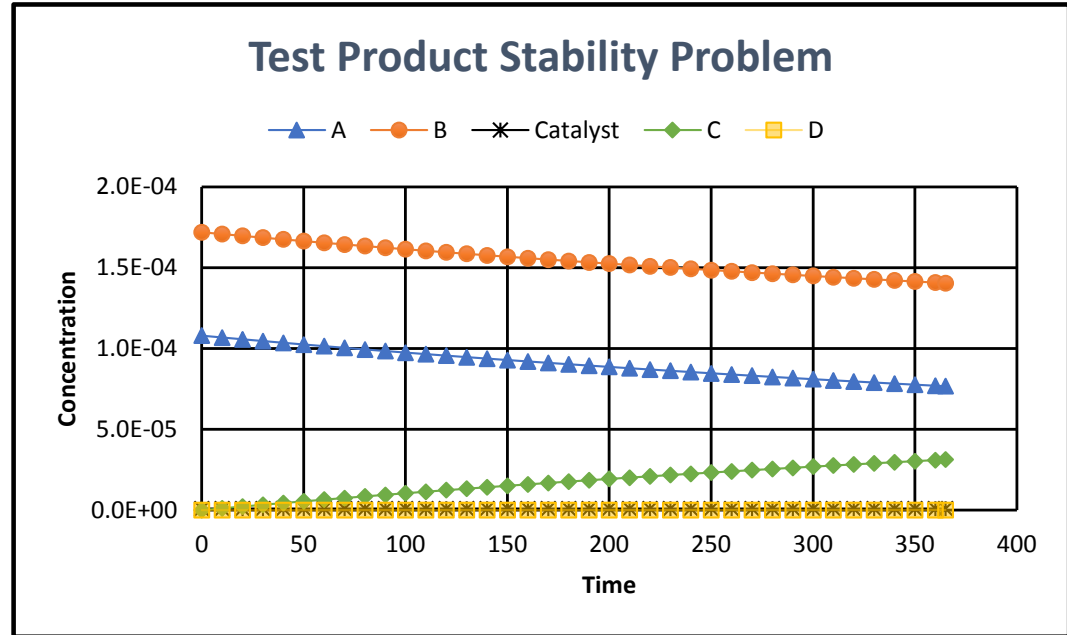
- It is desirable to have variables and equations scaled to $O(1)$
 - ◆ $0.01 \leq \text{scaled variable} \leq 100$
 - ◆ Median of scaled equation coefficients = 1
- It would be undesirable to maintain two separate versions of CheK with different internal units to provide scaling
 - ◆ Implemented an automatic scaling that is indifferent to units of measure (Process Engineering vs Product Stability)
 - ◆ Scaling factors adjusted based on the input data
 - The input data, of course, must be dimensionally consistent
- Solve the problem in terms of $\ln_concentration$ and $\ln_reaction_rate$ *as variables* of optimization
 - ◆ $reaction_rate = k \prod_{i \in Reactant} concentration_i^{v_i}$ becomes
 - ◆ $\ln_reaction_rate = \ln_k + \sum_{i \in Reactant} v_i \ln_concentration_i$
 - Reformulated expression is linear in the case of constant v

- After scaling and reformulation, could not get the “full-space” (all time periods simultaneously) model to solve
- Used an optimization to initialize the concentration profile for fixed rate of change
 - ◆ Initialization ~500 iterations
 - ◆ Simultaneous solution ~2000 iterations
- Developed a procedural initialization based on 1st-degree collocation approximation between collocation points (Euler)
 - ◆ No optimization now needed for initialization
 - ◆ “Full-space” solution ~13 iterations
- Implemented Finite Element by Finite Element initialization (integration) to handle more complex kinetic networks and multiple experiments
 - ◆ ~6 iterations per Finite Element (x365 total Finite Elements)
 - ◆ Initialized “full-space” model then solves in 6 iterations



“Catalyst” is a ubiquitous component in the solution matrix.

It is not an added component to accelerate the reaction.



- The goal of a Product Stability experimental campaign is to predict the amount of product degradation after a long time period (e.g. two years) as the product makes its way through the supply chain
 - ◆ Predicted concentration of degradation product(s)
 - ◆ Confidence limits on prediction(s)
- The reactions are slow and the experimental temperatures have a limited range, based on anticipated supply chain temperatures.
 - ◆ Vials of various concentrations (initial conditions) are stored in one of a limited-number of temperature-controlled rooms
- Depending on the initial conditions and temperatures, a single experiment may run from three to six months (desired) or more
- The duration of the experimental campaign necessitates parallel Design of Experiments (DoE)

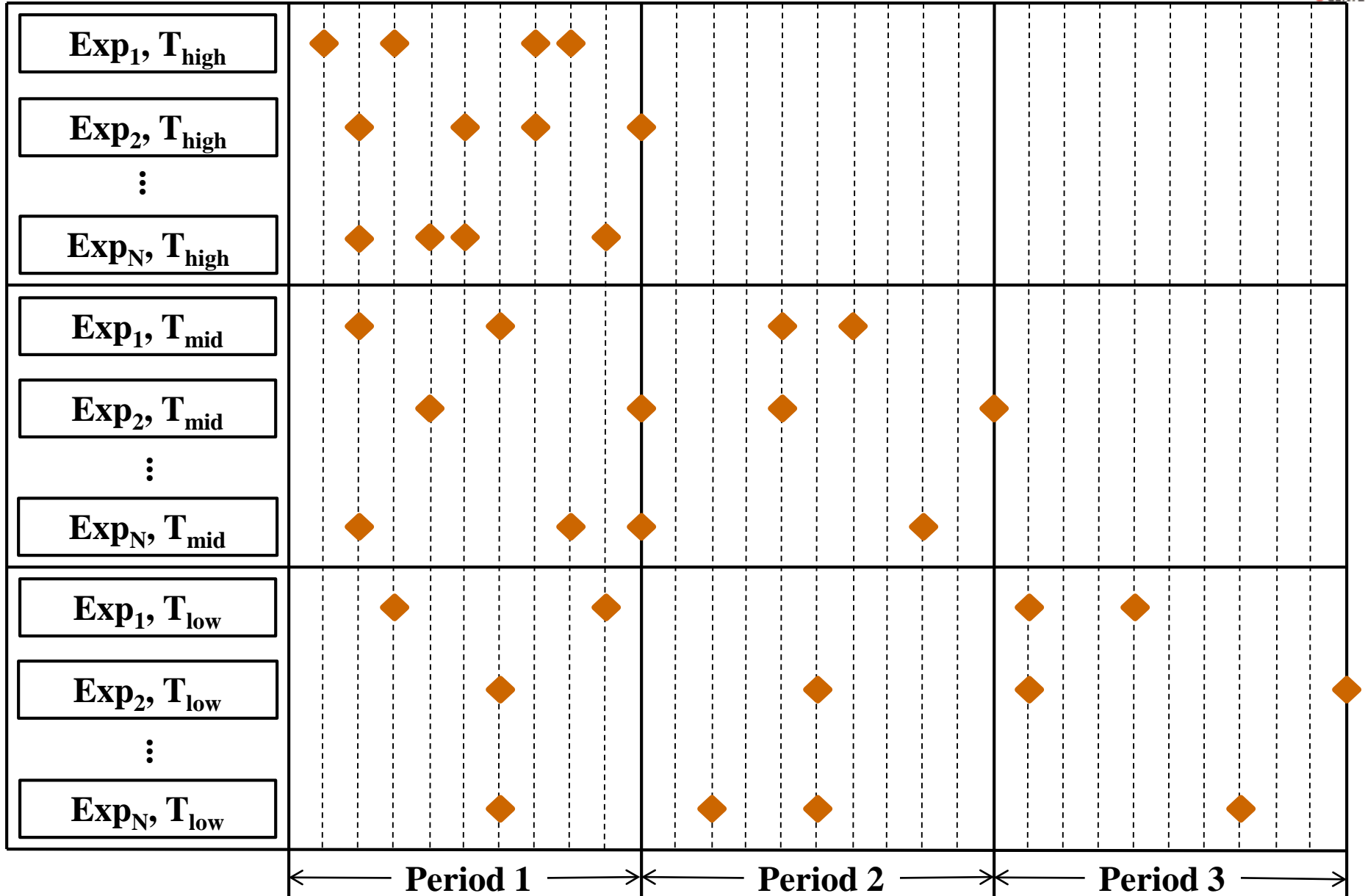
- A parallel design may incorporate combinations of design objectives
- Currently, Cholesky and Schur matrix decompositions are available to perform the following design objectives:
 - ◆ E-optimal: Maximize the minimum eigenvalue of the Information Matrix
 - In parallel DoE, sequentially generate design points to maximize the value of each of the eigenvalues, starting with the smallest
 - ◆ D-optimal: Maximize the determinant of the Information Matrix (minimizes the volume of the joint confidence region)
 - ◆ A-optimal: Maximize the trace of the Information Matrix
 - ◆ Anti-Correlation: Minimize the covariance between selected parameter pairs
- Optimized design objective values can be constrained in subsequent designs, so that one obtains the best value for a new objective that does not worsen previous objective values

- Typically, there is not an abundance of kinetic data for the reactions in the Consumer Products area
 - ◆ Little or no experimental data is initially available
 - ◆ Wide bounds on permissible parameter values around initial estimates
- Desire to make efficient usage of Analytical Chemistry resources and limited experimental space
- Robust optimization (optimization under uncertainty) identifies the worst combination of parameter values for the desired experimental design objective for each experiment
 - ◆ Parameter values only constrained by lower and upper bounds
- Robust Optimal Design thus seeks to find the best experimental design point for each experiment based on the most conservative set of parameter values for the particular design objective

- Observation 1: For a single reaction, the profiles of identical experiments (initial concentrations) at different temperatures trace identical “scaled profiles”
 - ◆ The profile at a higher temperature is a “condensed” (in time) version of the profile at a lower temperature
- Observation 2: Optimal sampling time profile will be shorter at higher temperatures, so higher temperature experiments can be designed and run sequentially
 - ◆ Within the overall experimental campaign duration
 - ◆ Using increasingly tighter parameter estimates based on data accumulated in the earlier phase of the experimental campaign

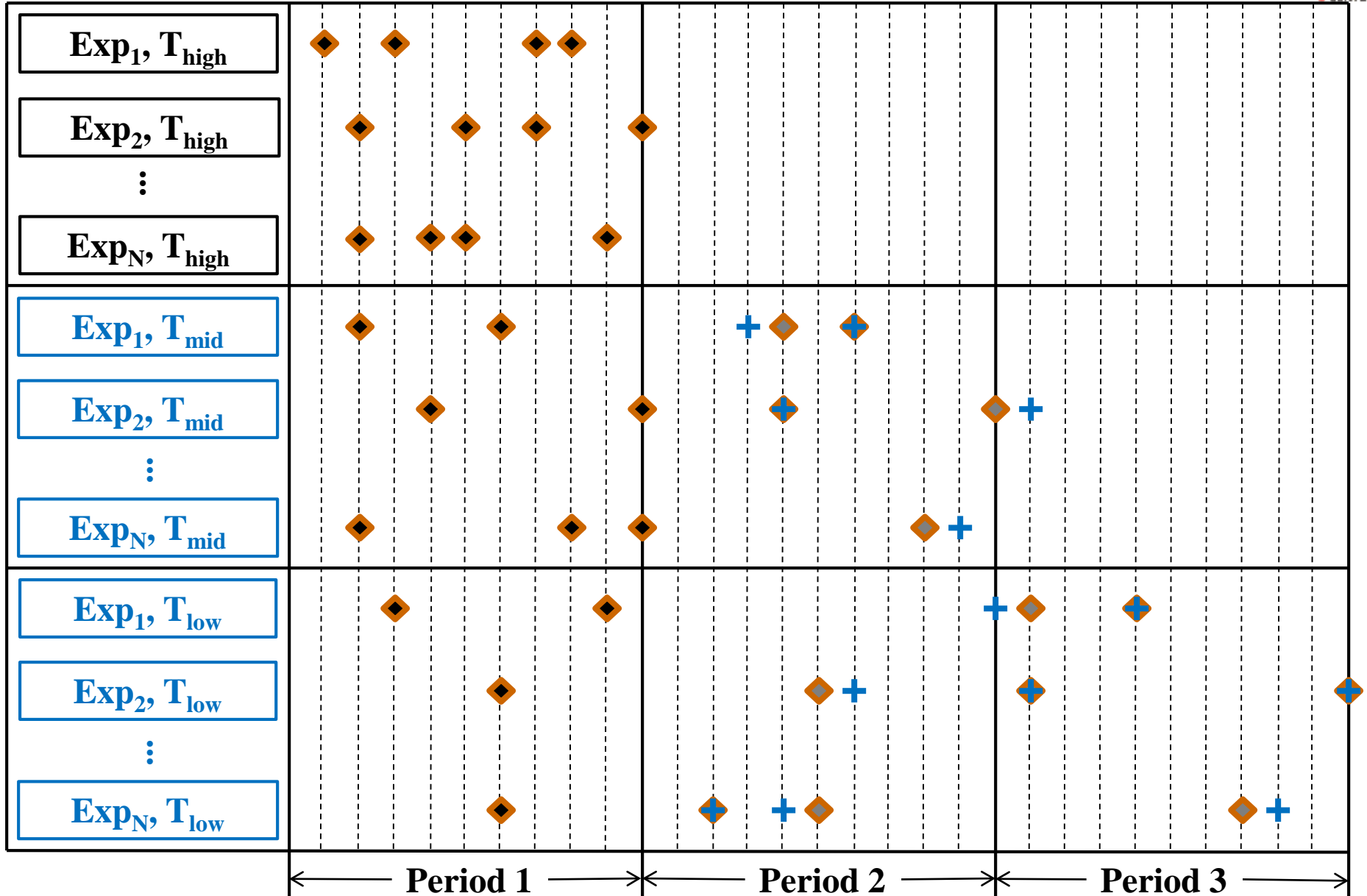
- Perform intermediate parameter regression based on data as it becomes available on a period by period basis
 - ◆ Multiperiod Design of Experiments with sequentially improved parameter estimates
 - ◆ Recourse 1: Adjust *optimal future sampling times* for experiments already in progress
 - ◆ Recourse 2: Design *additional (new) experiments* at intermediate and higher temperatures
 - Limited by the overall campaign duration
 - Sequentially improved designs due to incorporation of new information from accumulated measurements data
- For illustrative purposes in the following “cartoon” slides, assume that an experiment proceeds
 - ◆ Two times as fast at T_{high} compared to T_{mid}
 - ◆ Three times as fast at T_{high} compared to T_{low}

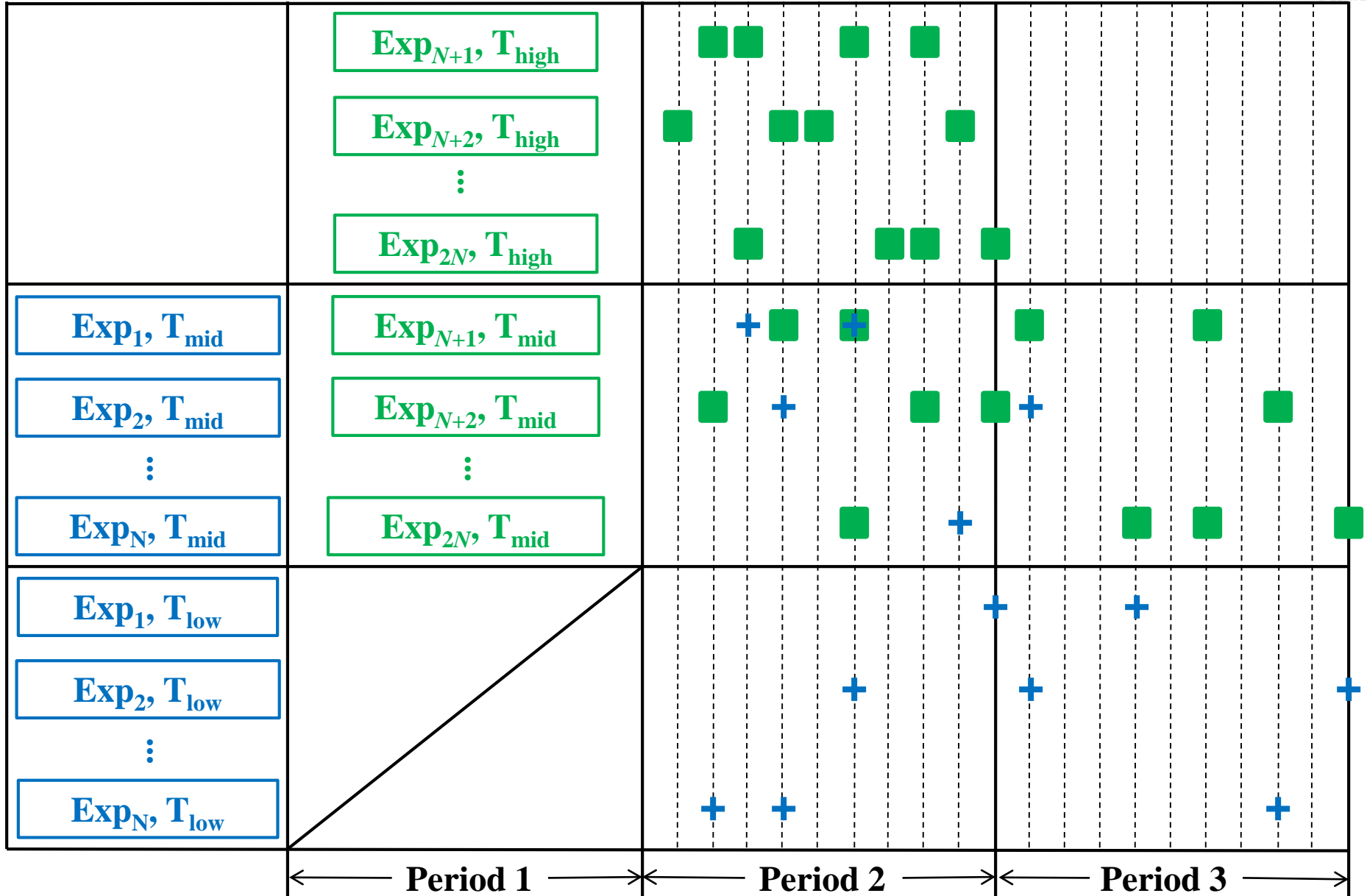
(For Illustration Assume Same Initial Conditions for each n)



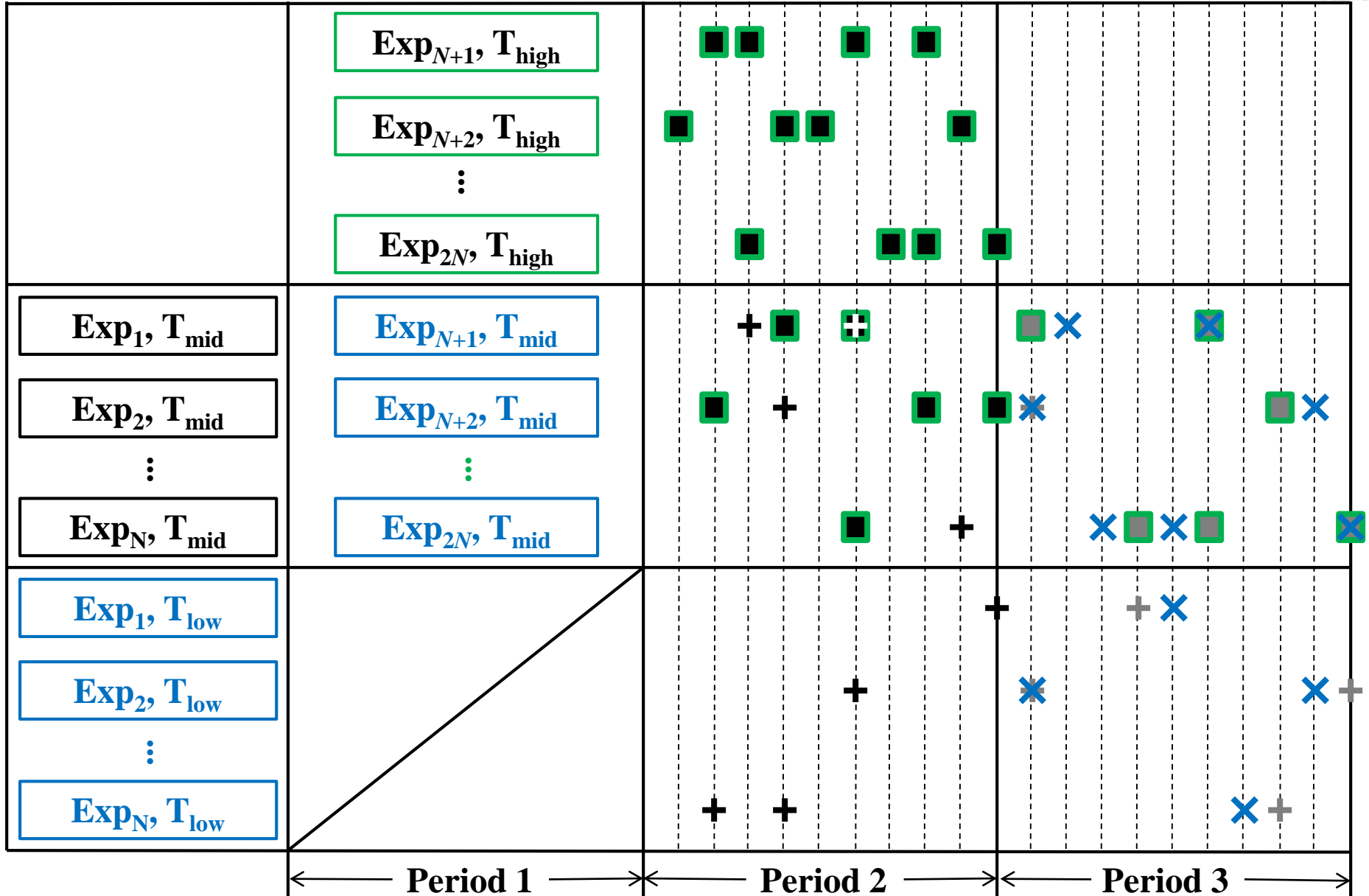
◆ Initial Sampling Times

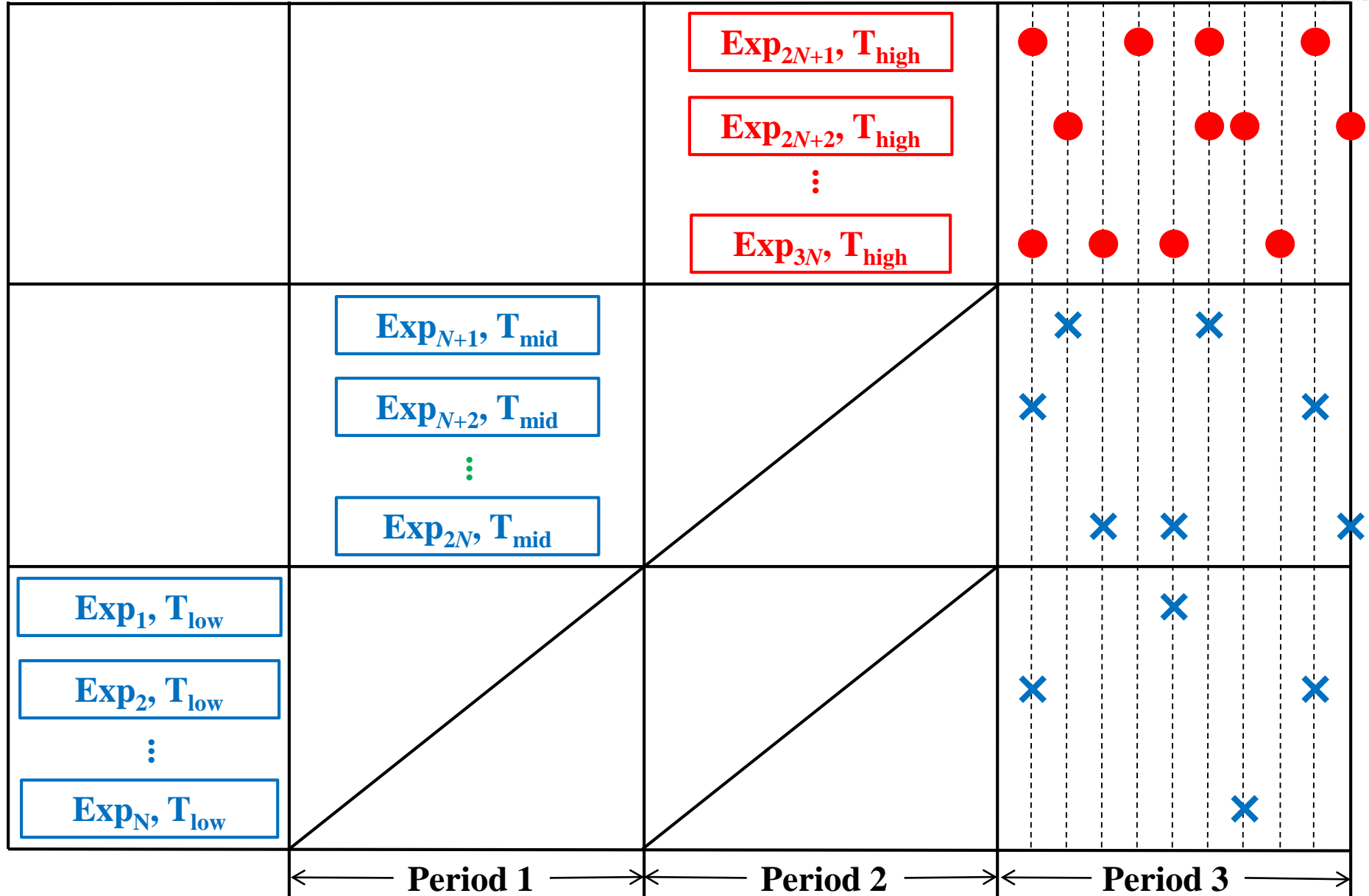
Update Parameter Estimates after Period 1 and Re-optimize Future Sampling Times with New Estimates





Update Parameter Estimates after Period 2 and Re-optimize Future Sampling Times with New Estimates





Summary of Adjusted Sampling Times and Sequential Experiments Using Parallel Design with Recourse

