

Piecewise Linear Approximation and Branch-and-Refine Algorithm for PX Tank Sizing under Uncertainty Problem

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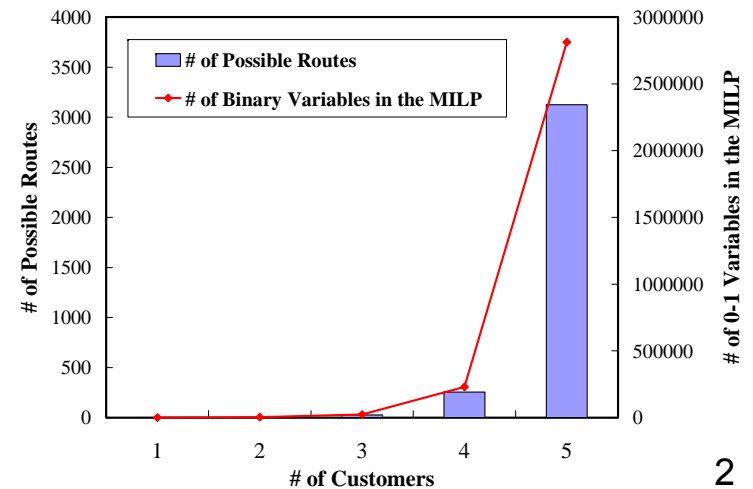
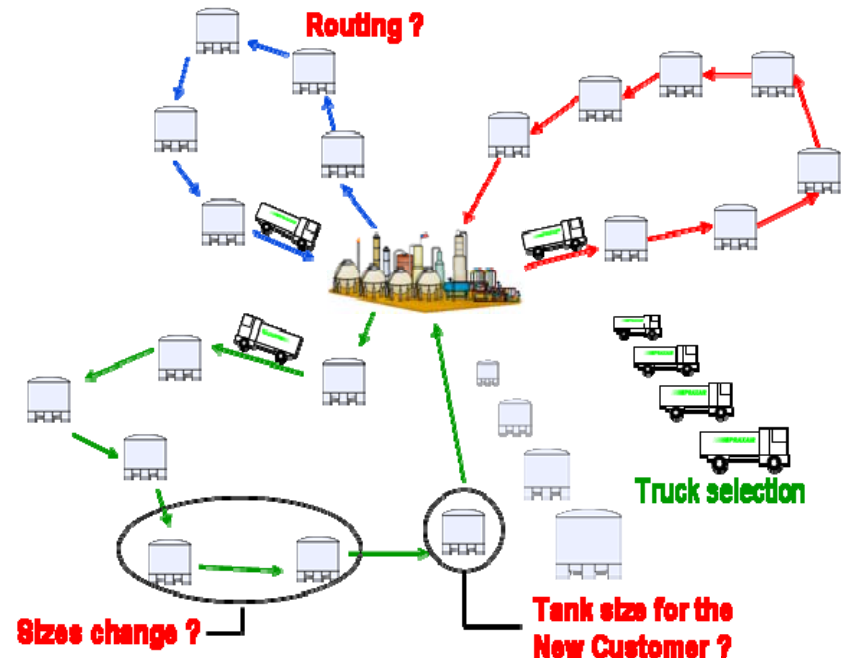
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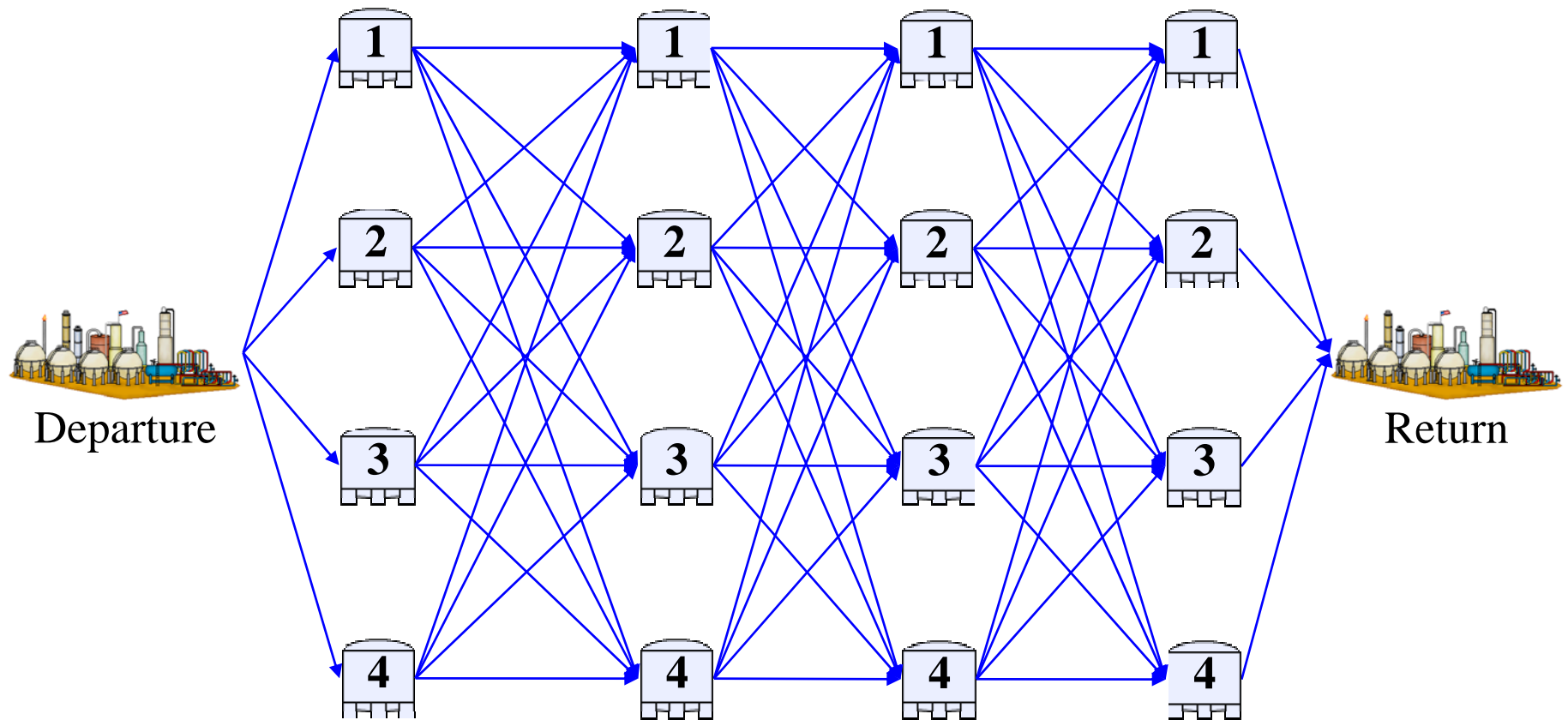
EWO Meeting March 10, 2010

Vehicle Routing – Tank Sizing Problem

- **Tank Sizing**
 - ◆ Tank installation, upgrade & downgrade
 - ◆ Several available discrete tank sizes
 - ◆ Safety stock optimization for uncertainty
- **Vehicle Routing**
 - ◆ Several available truck sizes
 - ◆ Routing and timing decisions
- **Integration**
 - ◆ Tradeoff: **operating cost** vs. **capital cost**
 - ◆ Capture the effects of **customer synergies** and **truck availability**
 - ◆ Integration requires to solve “extended” routing problem for long term (e.g. **years**)
 - ◆ Integrated MILP model is **very large**



Complexity – 4 customer case



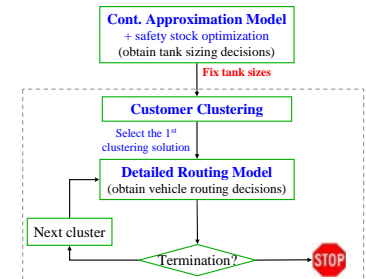
- ◆ **256 possible route**, **230,448 binary variables** in the MILP model for integrating tank sizing and vehicle routing

Modeling Challenges

- How to effectively integrate tank sizing with vehicle routing?

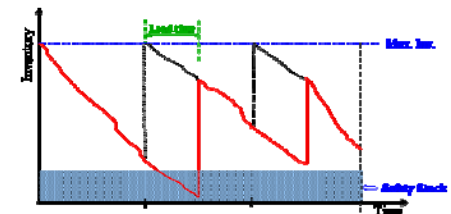
- ◆ Continuous approximation (CA) approach

- tradeoff capital and operating cost in the strategic level
 - reduce most integer variables with some nonlinearities



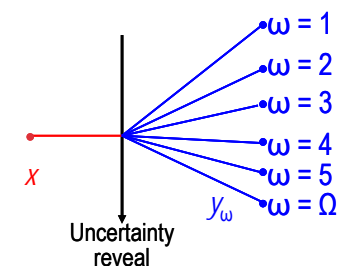
- How to optimize the safety stocks for **demand uncertainty**?

- ◆ Employ **stochastic inventory model**
 - ◆ Integrate safety stock optimization with tank sizing



- How to model the **uncertainty of adding/losing customers**?

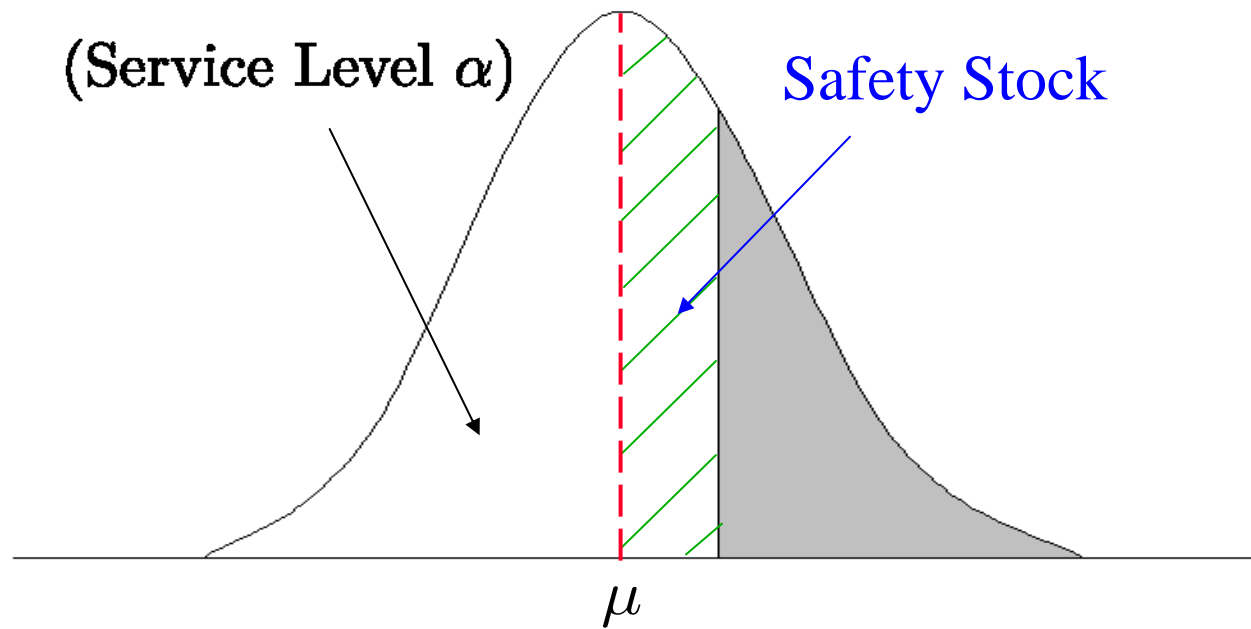
- ◆ Two-stage **stochastic programming**
 - ◆ A network structure for each scenario in each year



Optimal Safety Stock Level

$D \sim N(\mu, \sigma^2) \implies$ Safety Stock = $z_\alpha \sigma$, $P(z \leq z_\alpha) = \alpha$ (Service Level)

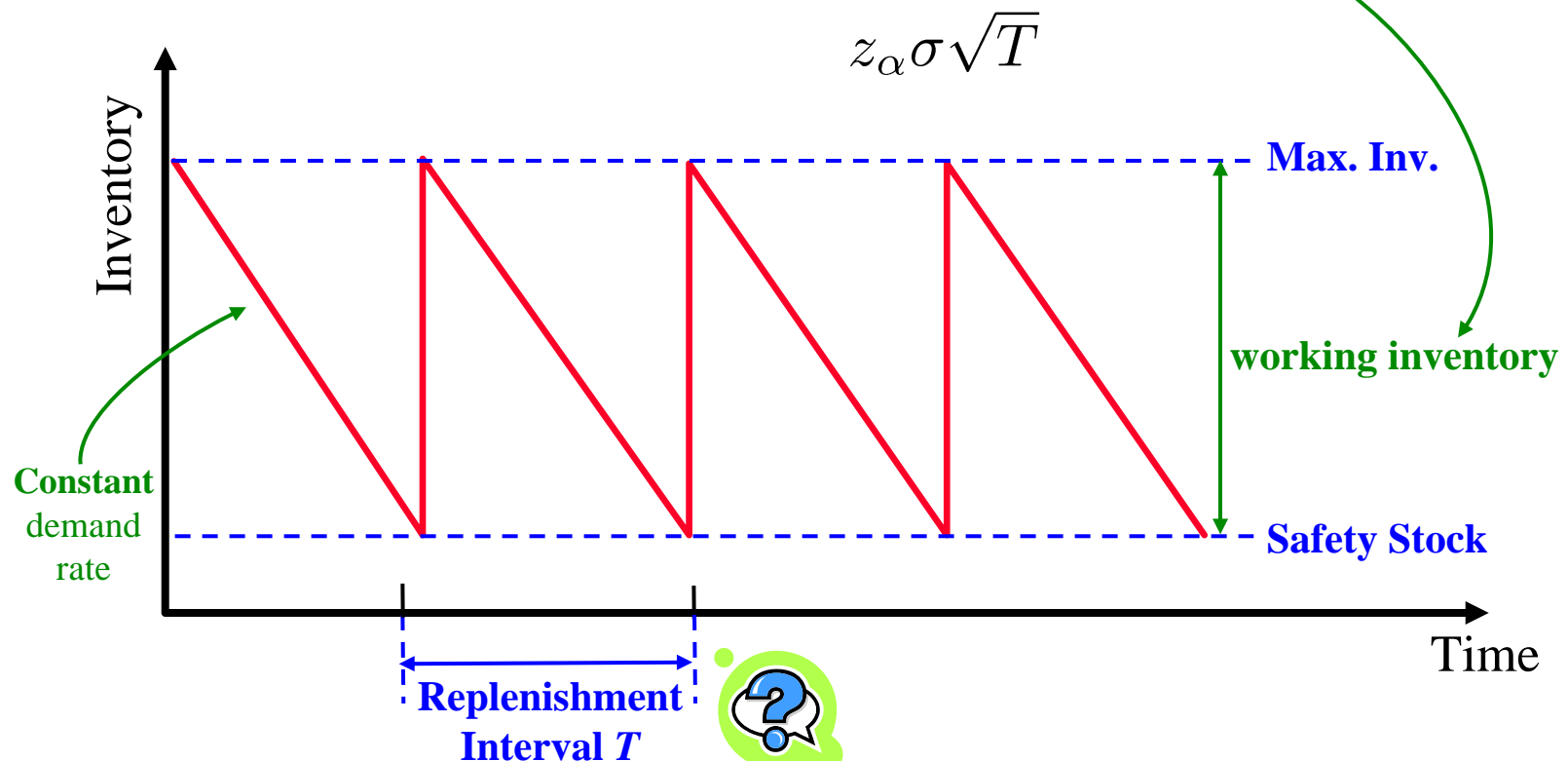
Lead time = $T \implies D \sim N(T \cdot \mu, T \cdot \sigma^2) \implies$ Safety Stock = $z_\alpha \sigma \sqrt{T}$



“Cyclic” Inventory-Routing

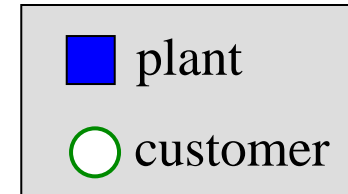


- **Key Assumption:** each customer is replenished in a “cyclic” way with interval T
- Required tank size \geq max. inv. = $\underbrace{\text{Safety Stock}}_{z_\alpha \sigma \sqrt{T}} + \underbrace{\text{demand rate} \times T}$

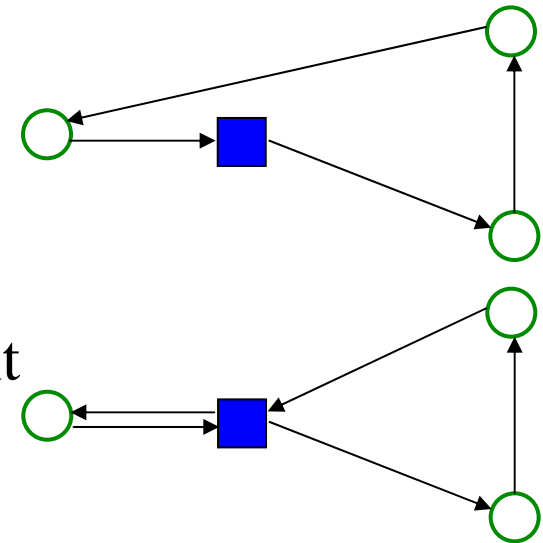


Routing & Replenishment in CAM

- $T = R / (\text{ave. speed})$
 - ♦ T - replenishment interval
 - ♦ R - minimum distance to visit all the customers in a cluster once
 - ♦ Average travelling speed is known



- If only **one trip** for each replenishment
 - ♦ $R = \text{TSP distance}$ of the cluster & plant
- If allowing **multiple trips** for replenishment
 - ♦ $R = ?$



CAM for Capacitated Routing Problems*

- **Bounds** for minimum routing distance R

$$R \approx 2 \lceil \frac{n}{q} \rceil r + (1 - \frac{1}{q}) \cdot \text{TSP}$$

- ◆ n – number of customers in the cluster
- ◆ q – capacity, max. number of customers that can be visited in one trip
- ◆ r – average distance from customers to the plant
- ◆ TSP – traveling salesman distance to visit all customers once

- **Examples**

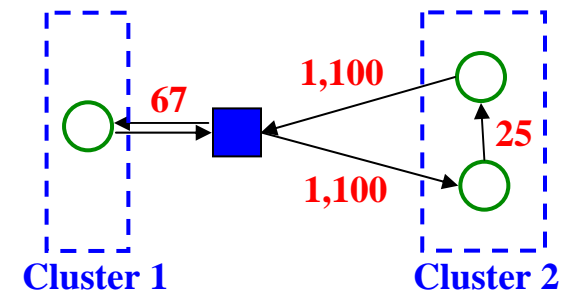
- ◆ Cluster 1: $q=1$, TSP=0, $r = 67$

$$2 \lceil \frac{n}{q} \rceil r + (1 - \frac{1}{q}) \cdot \text{TSP} = 2r = 2 \times 67 = 134\text{km}$$

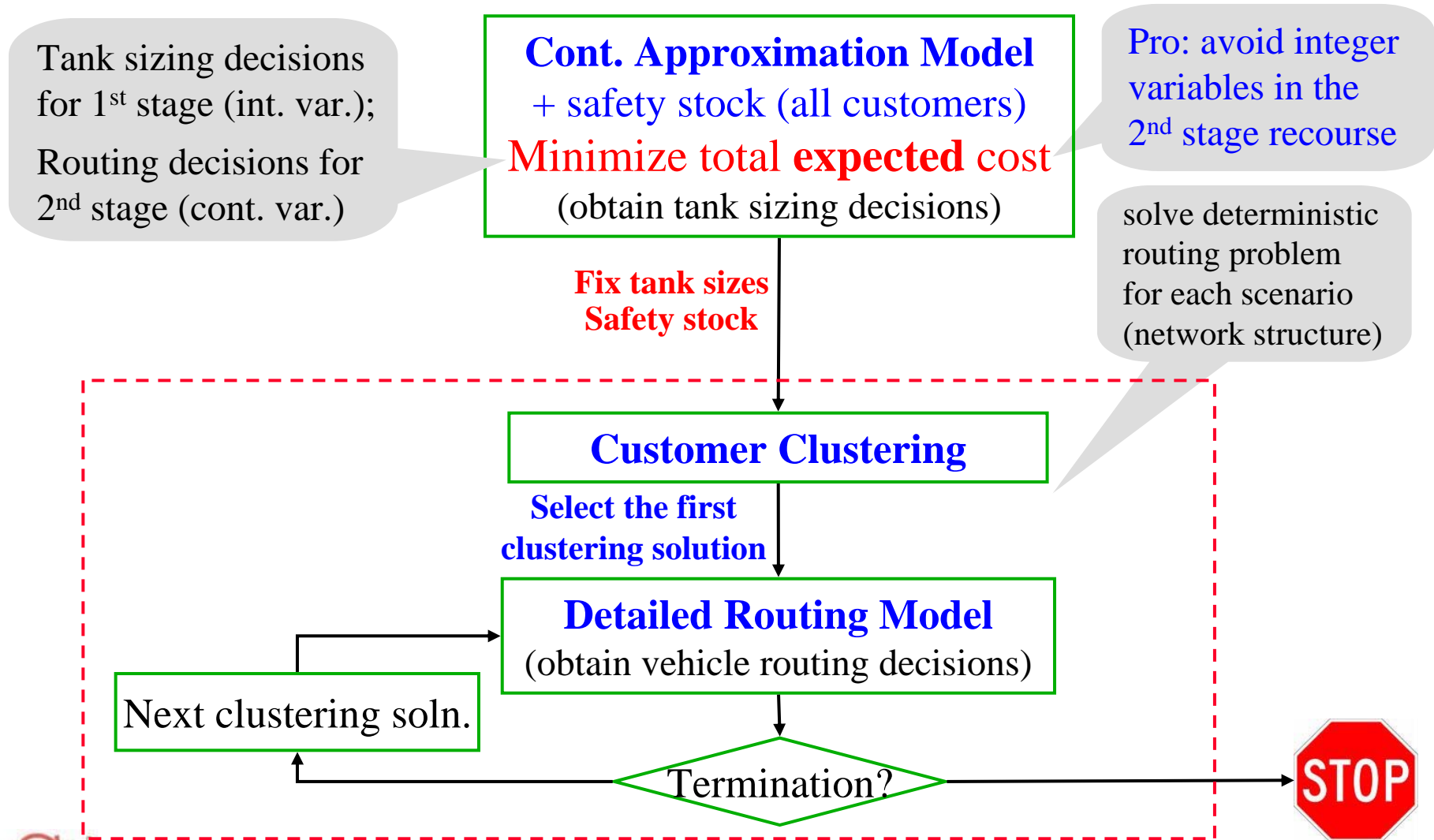
- ◆ Cluster 2: $q=1$, same as Cluster 1, $R = 4,400\text{km}$

- ◆ Cluster 2: $q=2$, TSP=50, $r = 1,100$

$$2 \lceil \frac{n}{q} \rceil r + (1 - \frac{1}{q}) \cdot \text{TSP} = 2r + \frac{\text{TSP}}{2} = 2,225\text{km}$$

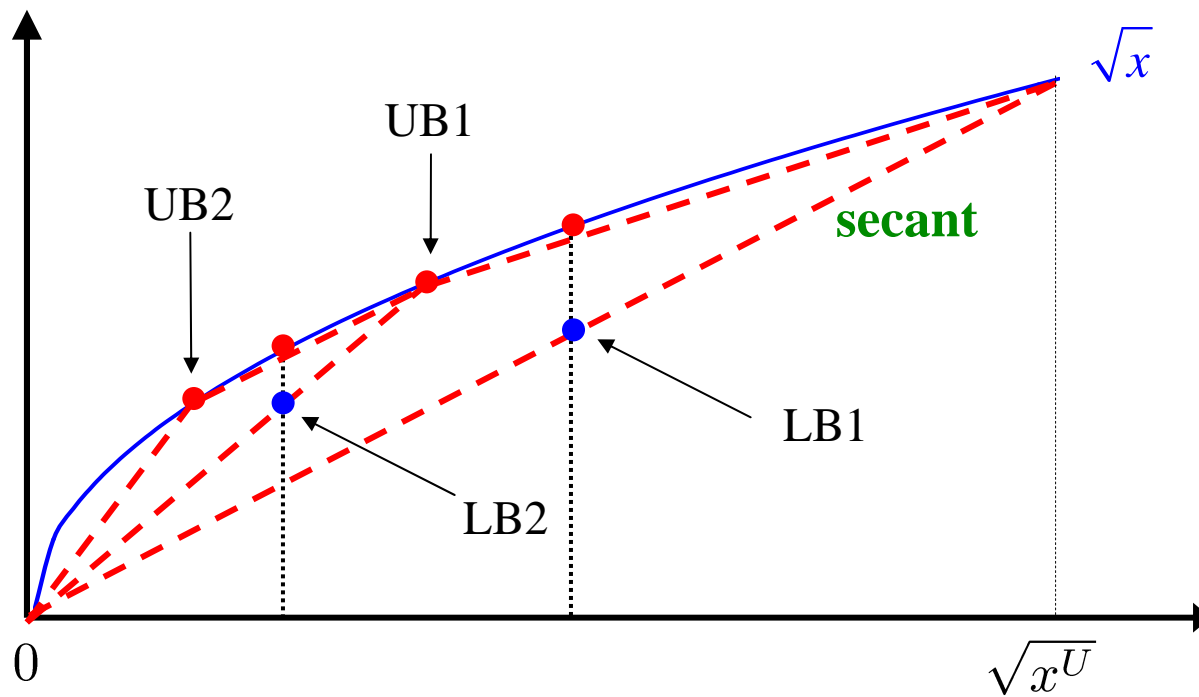


Decomposition for Scenario Planning



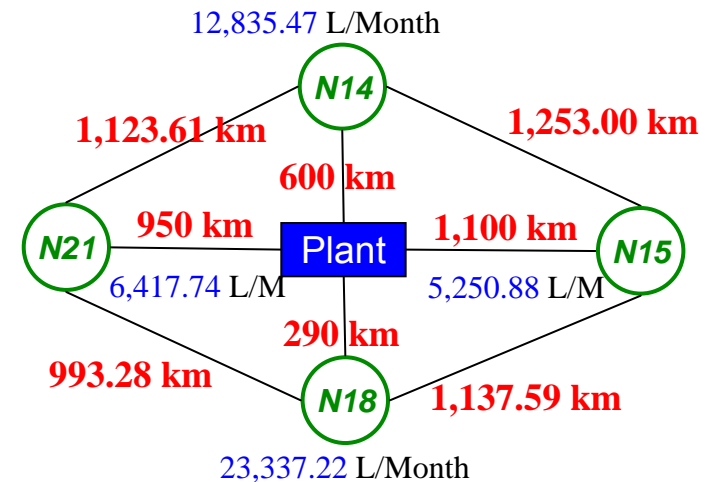
Branch-and-Refine Algorithm

- Global Optimization for MINLPs with *only* Univariate Concave Terms
 - ◆ Piece-wise linear approximation (MILP) provides **global lower bounds**
 - ◆ Feasible solutions provide **upper bounds** – solving a reduced MINLP
 - ◆ Increasing the number of pieces as iteration number increases

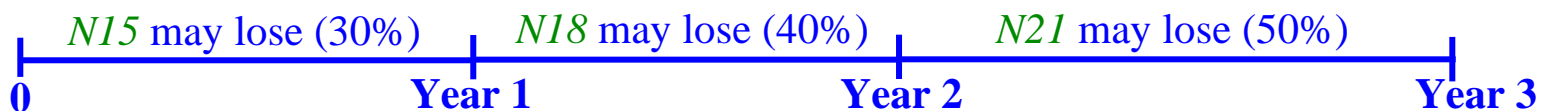


Case Study

- **Example 1: 3-year planning horizon**
 - ◆ 4 customers, 6 tank sizes, 6 types of trucks
 - *N14* will not lose by the end of Year 3
 - *N15* may lose in Year 1 with 30% chance
 - *N18* may lose in Year 2 with 40% chance
 - *N21* may lose in Year 3 with 50% chance



- **Scenario Tree:**

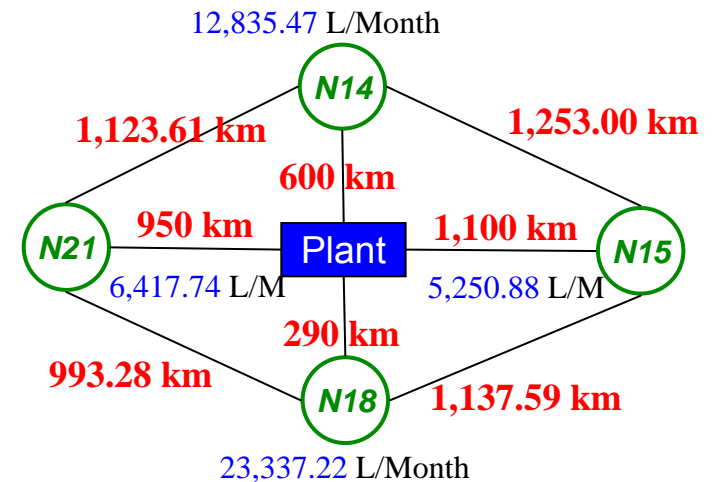


3 Existing Customer and 1 New Customer

- **Example 1: 3-year planning horizon**

- ◆ 4 customers, 6 tank sizes, 4 types of trucks

- *N14* will not lose by the end of Year 3
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 - *N21* may lose in Year 3 with 50% chance

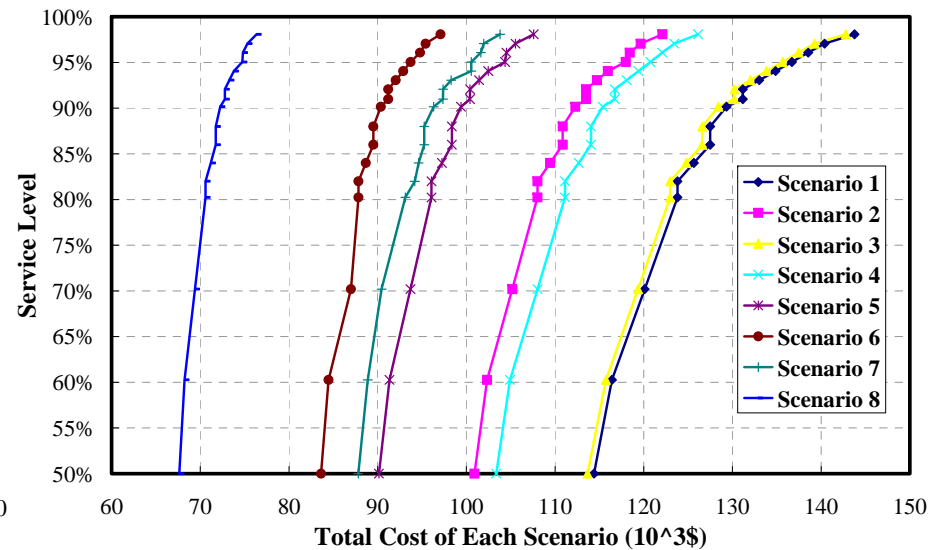
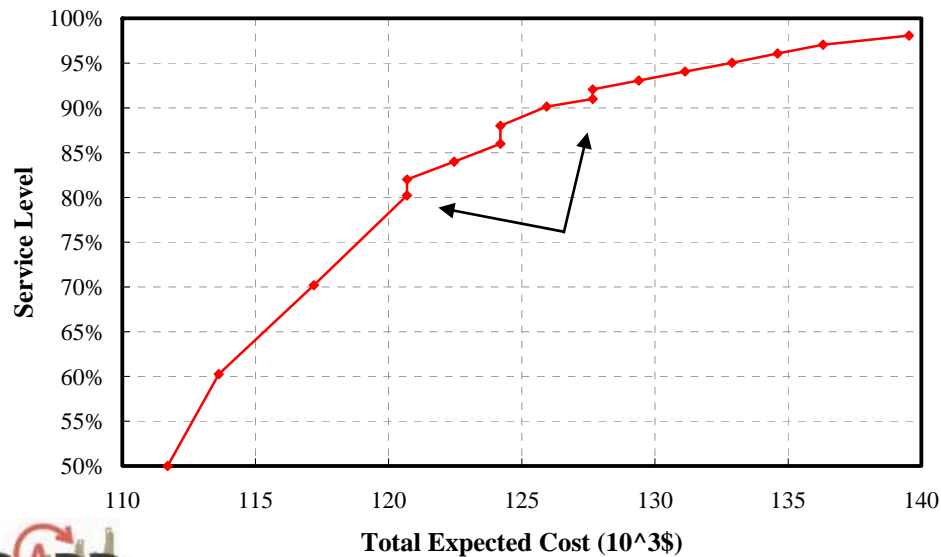
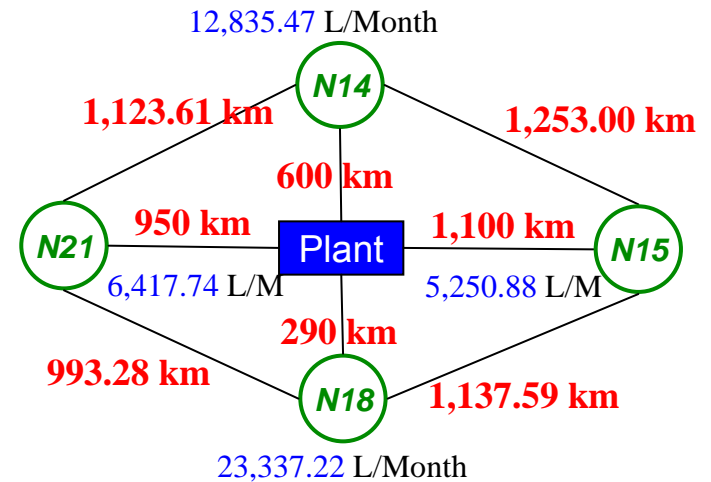


- **8 scenarios for two-stage stochastic programming**

- **S1** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.
 - **S2** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.
 - **S3** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.
 - **S4** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.
 - **S5** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.
 - **S6** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.
 - **S7** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.
 - **S8** – Y1: *N14, N15, N18, N21*; Y2: *N14, N15, N18, N21*; Y3: *N14, N15, N18, N21*.

Pareto Curves and Scenario Costs

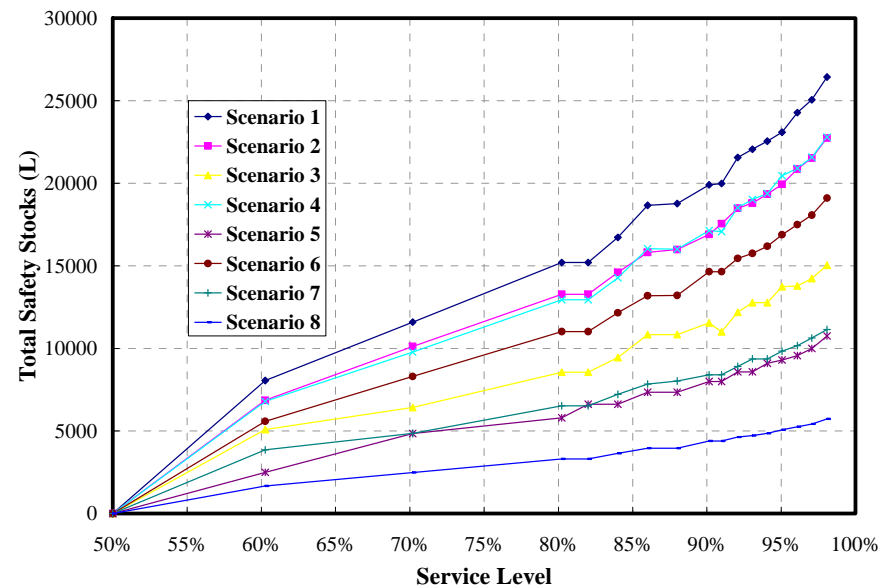
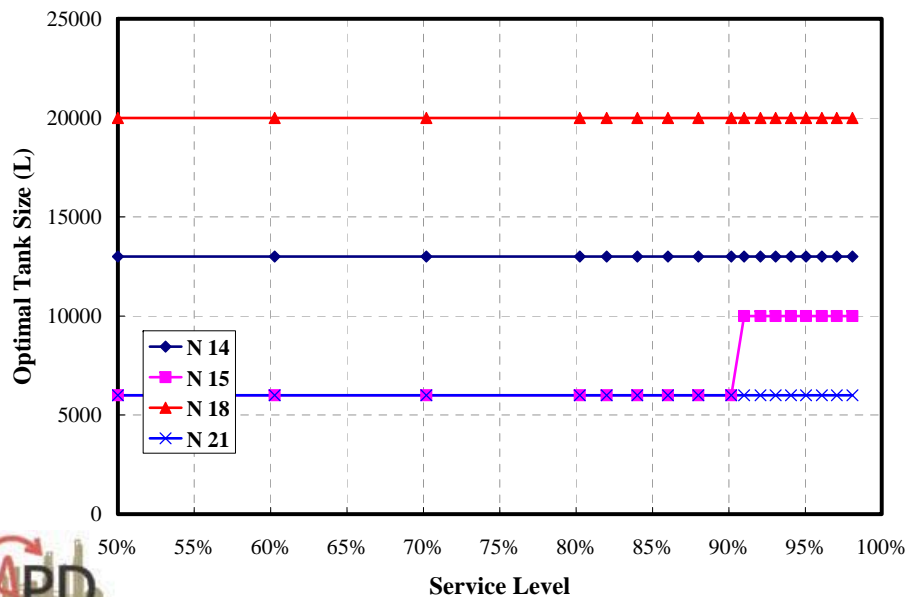
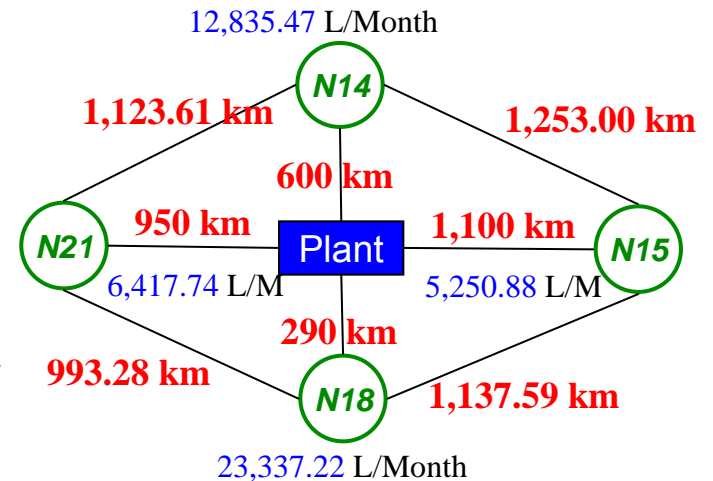
- CPU Times
 - ◆ Directly solved with DICOPT – **infeasible**
 - ◆ Directly solved with BARON – **> 7 days**
 - ◆ B&R algorithm (CPLEX 12 + DICOPT) – **285s** for all the 17 instances



Tank Sizes and Safety Stocks

- Model Statistics

- MINLP: 288 dis. var., 2,484 cont. var., 4,056 cons.
- MILP model: 408 dis. var., 2,724 cont. var., 4,344 cons.; Reduced MINLP: 48 dis. var., 2,484 cont. var., 4,056 cons. (5 iter.)



Optimal Routing Decisions

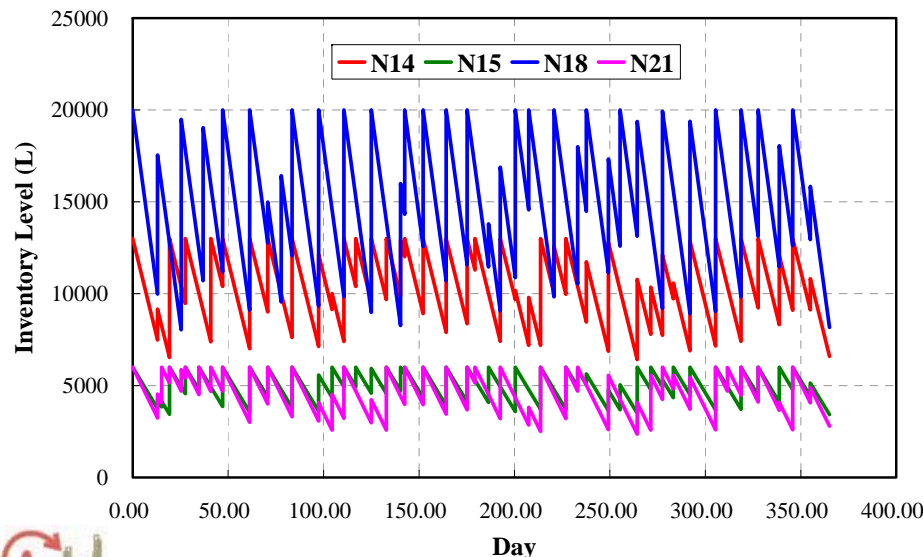
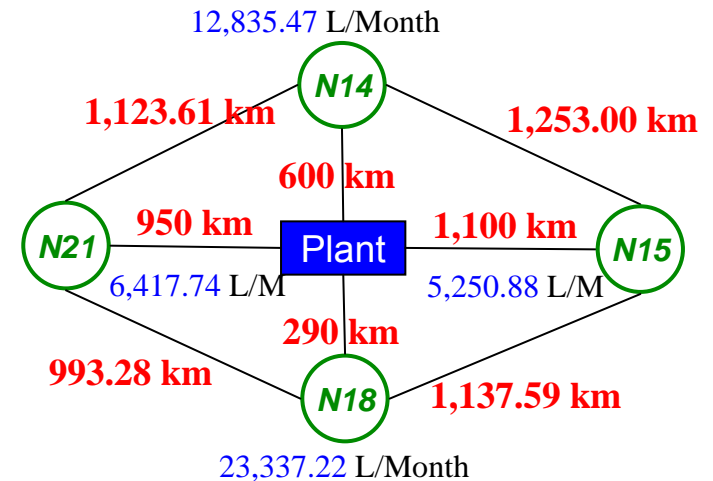
- Scenario 1 at Year 1, 90% Service Level

- Number of visits:

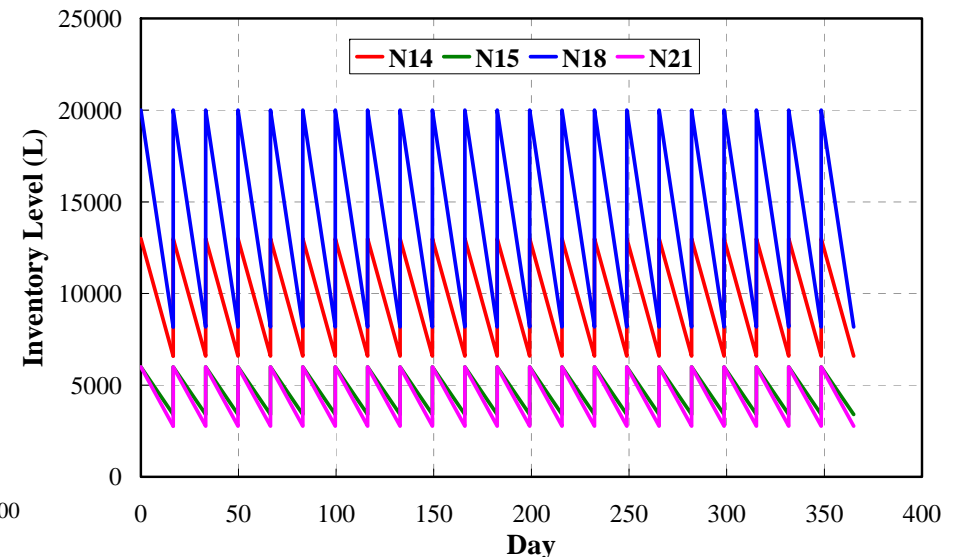
- $N14$: 17; $N15$: 17; $N18$: 37; $N21$: 18.

- Three routes are used:

- $P \rightarrow N18 \rightarrow N15 \rightarrow N14 \rightarrow N21 \rightarrow P$.
 - $P \rightarrow N18 \rightarrow N21 \rightarrow P$.
 - $P \rightarrow N18 \rightarrow P$.



Inventory profile from detailed routing



Inventory under continuous approximation